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The Fusion Distributed File System

Dongfang Zhao February 2015

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Outline

- Introduction
- FusionFS
 - System Architecture
 - Metadata Management
 - Data Movement
 - Implementation Details
 - Unique Features: virtual chunks, cooperative caching, distributed provenance
- Results
- Future Work

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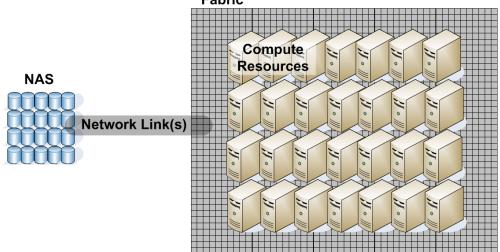
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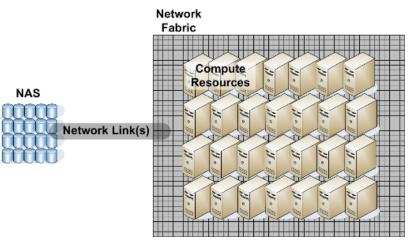
Background

- State-of-the-art high-performance computing (HPC) system architecture
 - Decades old
 - Has compute and storage resources separated
 - Was originally designed for compute-intensive workloads



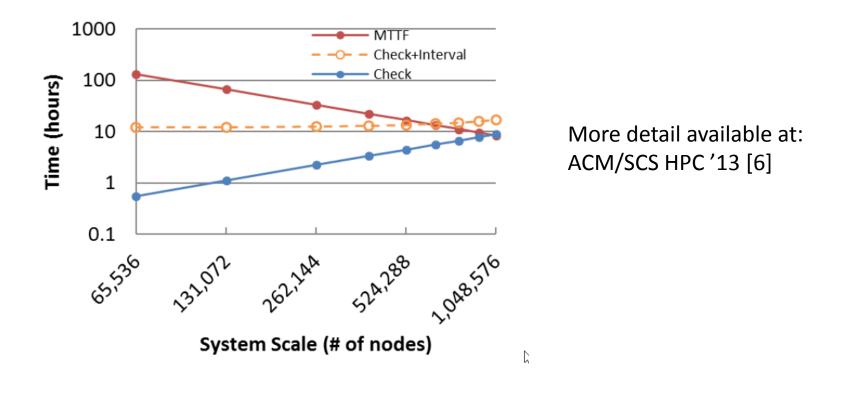
I/O Bottleneck

- Would this architecture suffice in Big Data Era at extreme scales? Concerns:
 - Shared network infrastructure
 - All I/Os are (eventually) remote
 - More frequent checkpointing



Challenges at Exascales

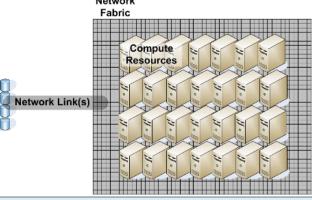
 Let's simulate, for example, checkpointing, at extreme scales



The Conventional Wisdom

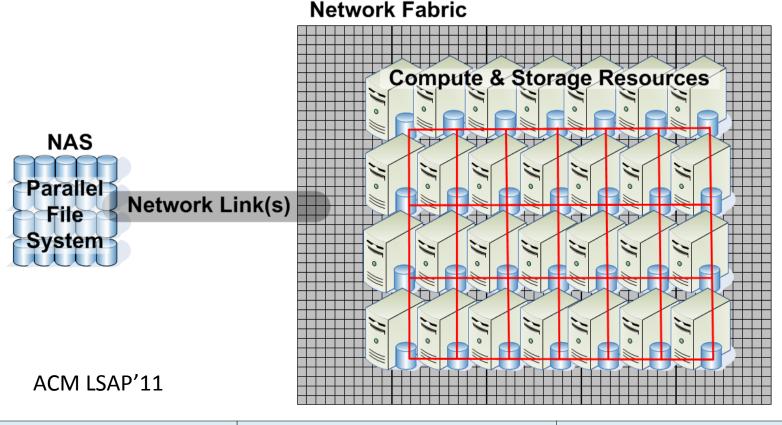
- Recent study to address the I/O bottleneck (without changing the current existing HPC architecture)
 - Ning Liu, et al. On the Role of Burst Buffers in Leadership-Class Storage Systems, IEEE MSST'12
 - Pillips Carns, et al. Small-file access in parallel file systems, IEEE IPDPS'09

NAS



Proposed Work

• We address the issue by proposing a new architecture: introducing node-local storage



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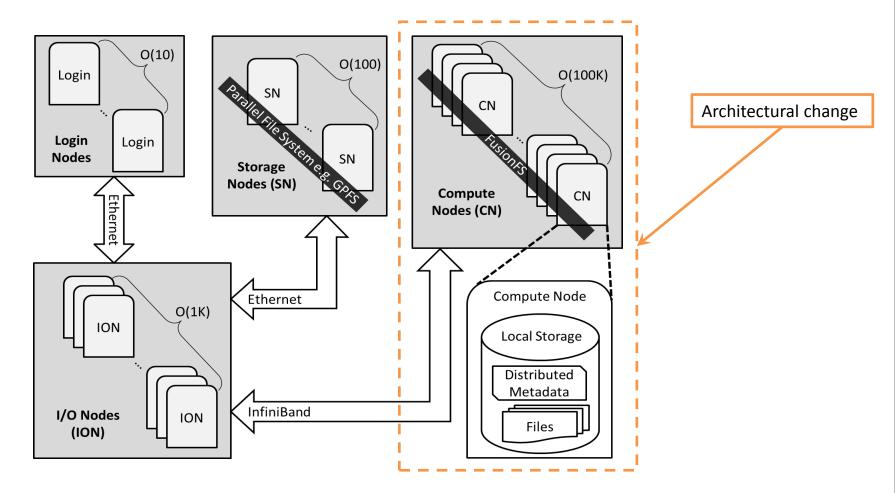
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Overview

- Goal: a node-local distributed storage for HPC systems
- Design principles
 - Maximal metadata concurrency
 - Distributed hash table
 - Optimal write throughput
 - Write local disk if possible

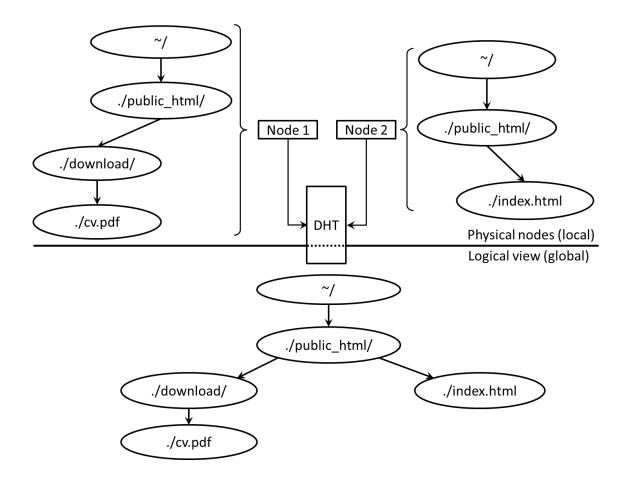
Architecture

• In IBM Blue Gene/P supercomputer:



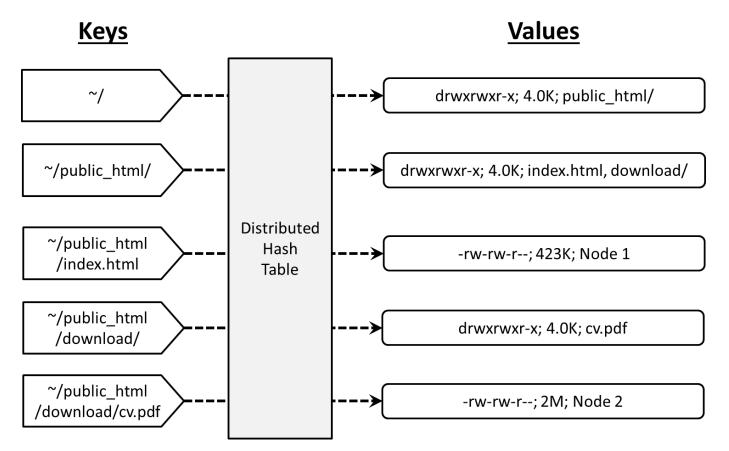
Directory Tree

• Physical-logical mapping



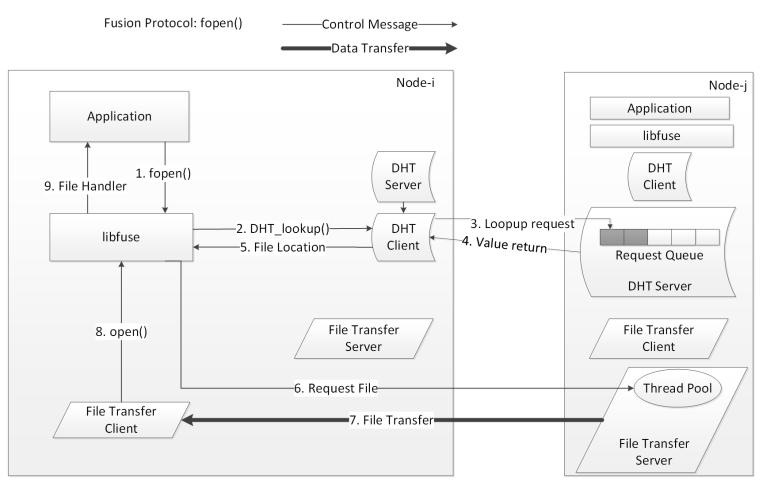
Metadata Management

• Directories vs. regular files



File Manipulation

• File open



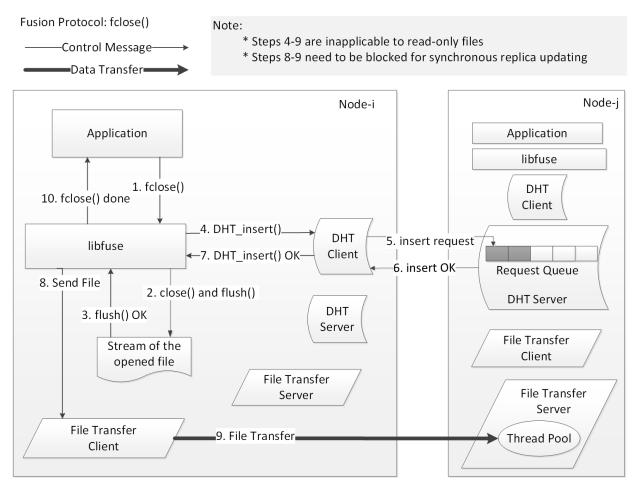
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File Manipulation

• File close



FusionFS Implementation

- C/C++
- Building blocks
 - FUSE (user-level POSIX interface)
 - ZHT (distributed hash table for metadata)
 - Protocol Buffer (data serialization)
 - UDT (data transfer protocol)
- Open source: <u>https://bitbucket.org/dongfang/fusionfs-</u> <u>zht/src</u>

Virtual Chunks

- One of features in FusionFS
- Goal: support efficient random accesses to large compressed scientific data

Background

- In Big Data Era, many data-intensive scientific applications' performance are bounded on I/O
- Two major solutions:
 - Parallelize the file I/O by concurrently read or write independent file chunks
 - Compress the (big) file before writing it to the disk, and decompress it before reading it
 - Could be done efficiently at the file system layer
 - transparent to end users

Conventional Wisdom

- File systems leverage data (de)compression in a naïve manner:
 - Apply the compressor when writing files
 - Apply the decompressor when reading files
 - Leave important metrics to the underlying compressing algorithms
 - Compression ratio
 - Computational overhead

Limitations

- File-level compression: computation overhead of read. E.g., read the latest temperature
 - Step 1: compress the entire 1GB climate data to 500MB file
 - Step 2: decompress the 500MB file to only retrieve the last few bytes
- Chunk-level compression: space overhead of write. E.g., write 64MB data with 4:1 compression ratio and 4KB metadata
 - 64K-chunk: 16MB + 4KB * 1K = 20MB

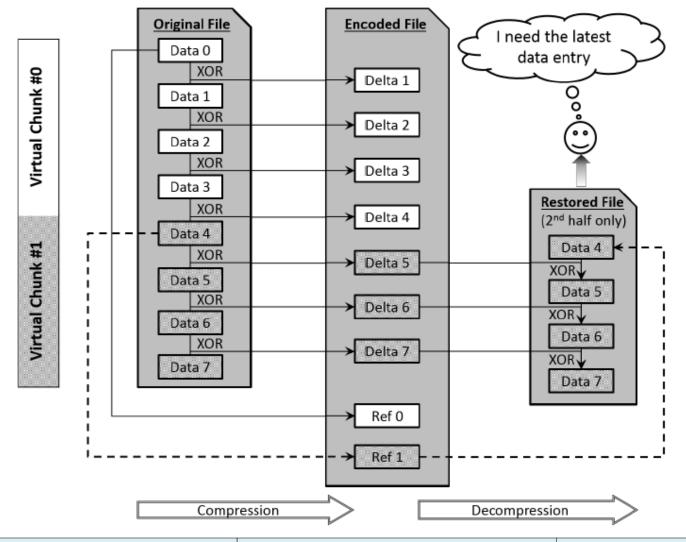
- No chunk: $16MB + 4KB \approx 16MB$

Key Idea

- Virtually split the file into smaller chunks but keep its physical entirety
 - Small chunk: fine granularity for random accesses
 - So to fix the computation overhead of file-level compression
 - Physical entirety: high compression ratio
 - So to fix the space overhead of (physical)chunk-level compression

Motivating Example

• A simple XOR-based delta compression

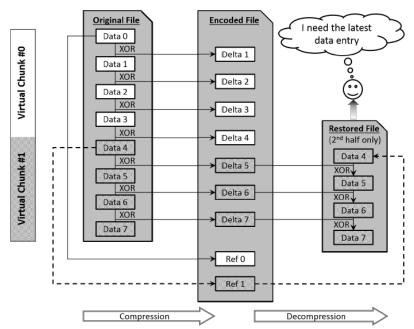


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Reference Placement

- Need to consider different strategies
 - In place
 - Pro: save one jump
 - Con: overhead for sequential read
 - Coalition
 - Beginning or end



Compression Procedure

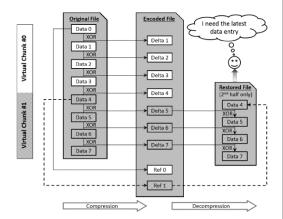
• Turns to be very straightforward:

Algorithm 1 VC Compress

Input: The original data $D = \langle d_1, \dots, d_n \rangle$ Output: The encoded data X, and the reference list D' 1: for (int i = 1; i < n; i++) do 2: $X[i] \leftarrow \text{encode} (d_i, d_{i+1})$ 3: end for 4: for (int j = 1; j < k; j++) do 5: $D'[j] \leftarrow D[1 + (j - 1) * L]$ 6: end for

• Runs efficiently:

Time complexity is O(n)



But... How Many Virtual Chunks?

- Extreme cases
 - 1 virtual chunk
 - Same as file-level compression
 - N virtual chunks (suppose there are N physical chunks in the file)
 - Same as (physical)chunk-level compression
- Find a number for good tradeoff?
 - Let's assume the requested file is located at the end of the virtual chunk

Number of Virtual Chunks

• Variables

Variable	Description
B_r	Read Bandwidth
B_w	Write Bandwidth
W_{i}	Weight of Input
W_o	Weight of Output
S	Original File Size
R	Compression Ratio
D	Computational Time of Decompression

• Optimum for end-to-end I/O

$$k_{opt} = \begin{cases} \lfloor \hat{k} \rfloor & \text{if } F(\lfloor \hat{k} \rfloor) > F(\lceil \hat{k} \rceil) \\ \lceil \hat{k} \rceil & \text{otherwise} \end{cases}$$

where

$$\hat{k} = \sqrt{n \cdot \frac{B_w}{B_r} \cdot \frac{W_i}{W_o} \cdot (\frac{1}{R} + \frac{D \cdot B_r}{S})}$$
(2)

and

$$F(x) = \frac{(x-1) \cdot S \cdot W_i}{x \cdot R \cdot B_r} + \frac{(x-1) \cdot D \cdot W_i}{x} - \frac{(x-1) \cdot S \cdot W_o}{n \cdot B_w}$$

• Short version

 $\hat{k}=\sqrt{n}$ (under some assumptions, refer to the paper for detail)

Decompression Procedure

- Algorithms omitted (refer to paper for detail)
- Key steps:
 - Find the latest reference (*r_last*) before the starting position of the request file
 - Decompress the file from *r_last*, until the end of the requested data
 - For file write, we also need to update values after the decompression, and re-compress the affected portion

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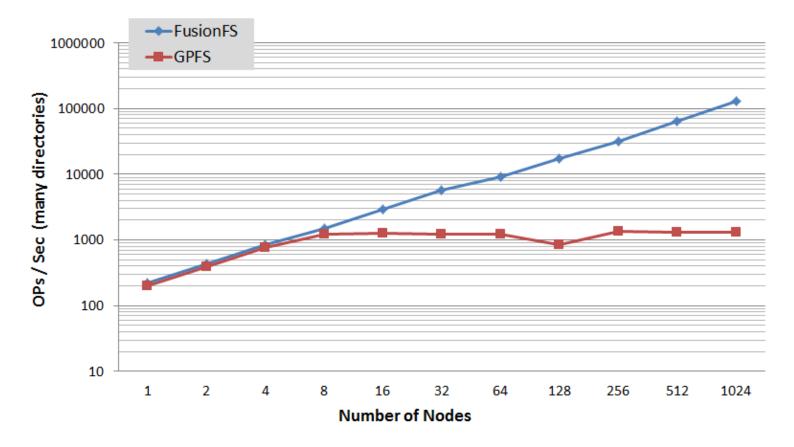
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Test Bed

- Intrepid (Argonne National Laboratory)
 - 40K compute nodes, each has
 - CPU: quad-core 850 MHz PowerPC
 - RAM: 2 GB
 - 128 storage nodes, 7.6 PB GPFS parallel file system
- Others not covered by this presentation
 - Kodiak, 1,024-node cluster at Los Alamos National Laboratory
 - HEC, 64-node Linux cluster at SCS lab
 - Amazon EC2

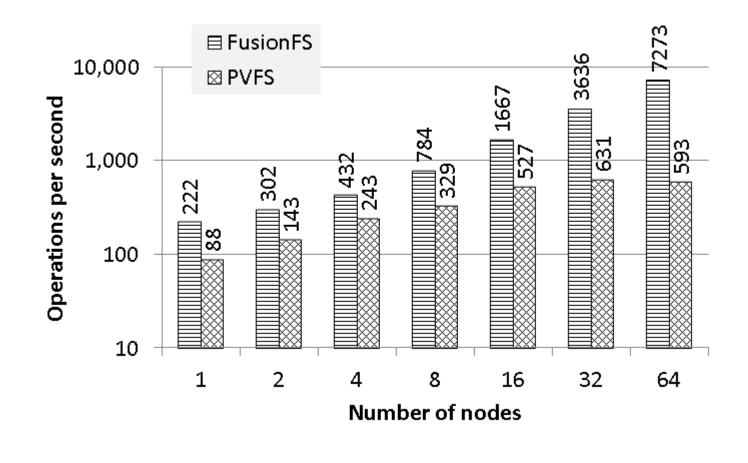
Metadata Rate

• FusionFS vs. GPFS



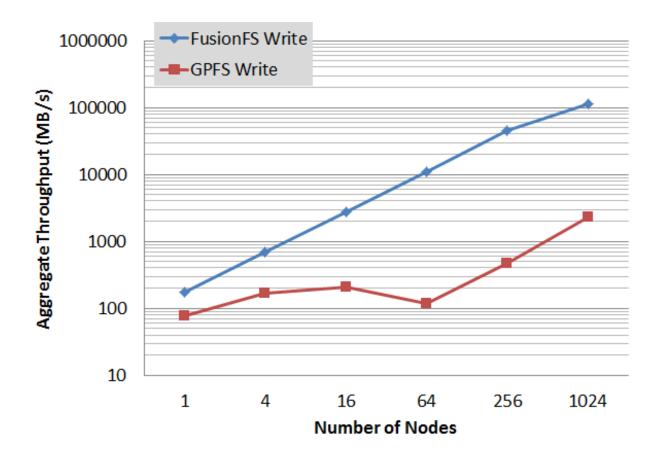
Metadata Rate

• FusionFS vs. PVFS



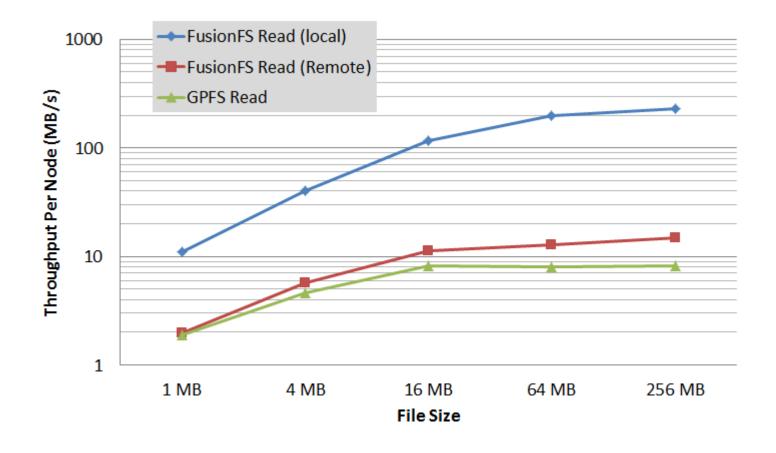
I/O Throughput

• Write, FusionFS vs. GPFS



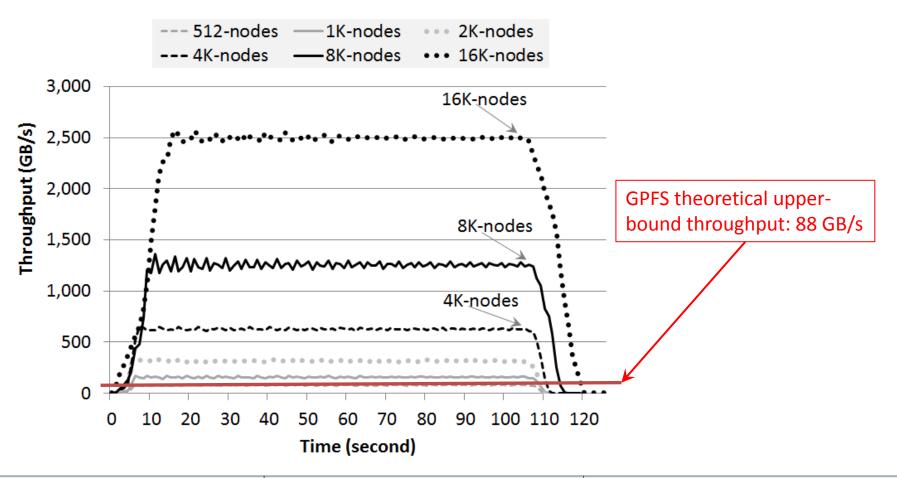
I/O Throughput

• Read, FusionFS vs. GPFS



I/O Throughput at Extreme Scale

• Peak: 2.5 TB/s on 16K nodes:



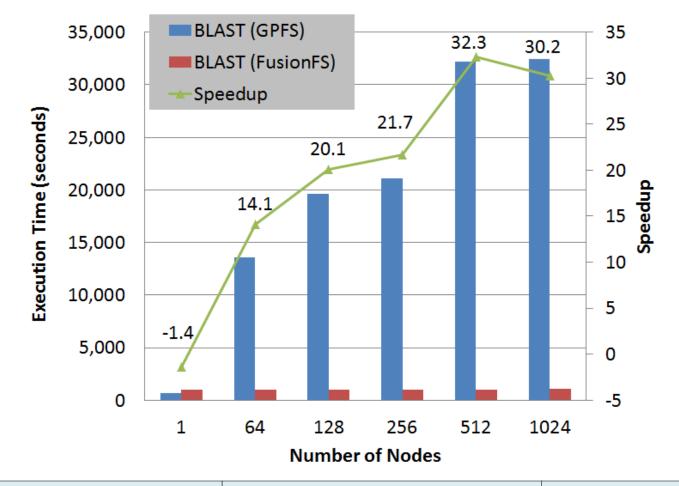
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The BLAST Application

- BLAST: Basic Local Alignment Search Tool
- A Bioinformatics application that
 - Searches one or more protein sequences against a sequence database
 - Calculates similarities
- Main idea: divide and conquer
 - Split the database and store chunks on different nodes
 - Each node searches the matching for assigned chunks
 - All searches are merged into the final results

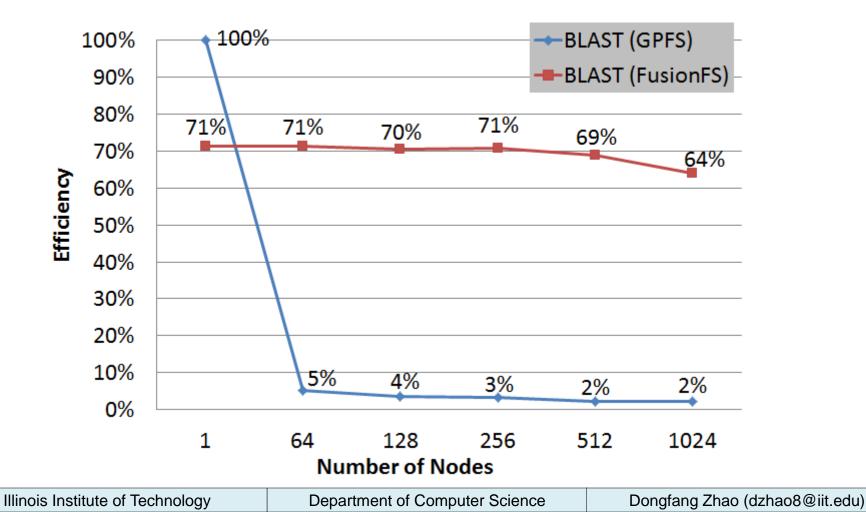
Execution Time

• FusionFS 30X faster on 1,024 nodes



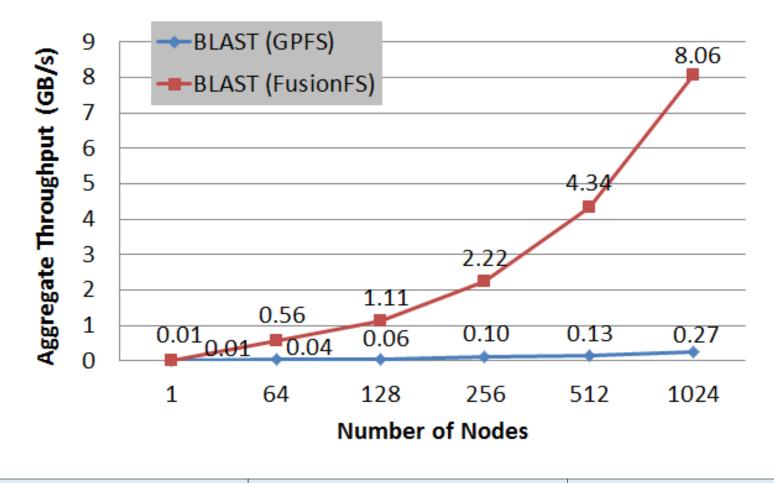
System Efficiency

• FusionFS's sustainable efficiency:



Data Throughput

• FusionFS is orders of magnitude higher



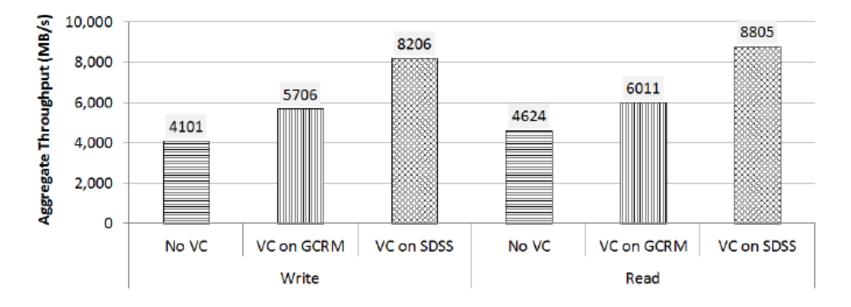
Virtual Chunks in FusionFS

- Setup
 - 64-node Linux cluster
 - each node has a FUSE mount point for POSIX and Virtual Chunk module
- Data set
 - GCRM: Global Cloud Resolving Model
 - 3.2 million data entries; each entry has 80 singleprecision floats
 - SDSS: Sloan Digital Sky Survey

Result

- Number of virtual chunks: sqrt(n)
- Compression ratio

– GCRM 1.49 vs. 2.28 SDSS



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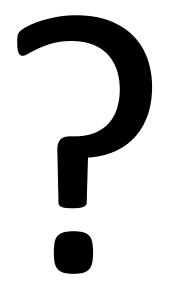
Simulation of FusionFS at Exascales

- Approach
 - Leverage CODES framework to develop a simulator (FusionSim) to simulate FusionFS at
 - Validate FusionSim with FusionFS traces
 - Predict FusionFS performance at Exascales with the Darshan logs

Integrate FusionFS with Swift

- Approach
 - Expose/develop the FusionFS API for Swift
 - Test FusionFS with the Swift applications
 - Ultimately an ecosystem from data management to the underlying filesystem as an analogy of Hadoop stack:
 - MapReduce <-> Swift
 - HDFS <-> FusionFS

Questions



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