Design Multicast Protocols for Non-Cooperative Networks

WeiZhao Wang*

Xiang-Yang Li^{*} Zheng Sun[†] Yu Wang[‡]

Abstract-Conventionally, most network protocols assume that the network entities who participate in the network activities will always behave as instructed. However, in practice, most network entities are selfish: they will try to maximize their own benefits instead of altruistically contributing to the network by following the prescribed protocols. Thus, new protocols should be designed for the non-cooperative network that is composed of selfish entities. In this paper, we specifically show how to design truthful multicast protocols for non-cooperative networks such that these selfish entities will follow the protocols out of their own interests. By assuming that every entity has a fixed cost for a specific multicast, we give a general framework to decide whether it is possible and how, if possible, to transform an existing multicast protocol to a truthful multicast protocol by designing a proper payment protocol. We then show how the payments to those relay entities are shared *fairly* among all receivers so that it encourages collaboration among receivers. As running examples, we show how to design truthful multicast protocols for several multicast structures that are currently used in practice. We also conduct extensive simulations to study the relation between the payment and the cost of the multicast structure. Our simulations show that multicast not only saves the total resources, but also benefits the individual receiver even in selfish networks.

Index Terms—Combinatorics, economics, non-cooperative, multicast, payment, sharing.

I. INTRODUCTION

Since first introduced by Deering in [1] and the audiocast experiment by IETF, multicast has received more and more attentions over the past few years due to its resource sharing capability. In multicast, there is a topology, either a tree or a mesh, that connects the source to a set of receivers, and the packet is only duplicated at the branching nodes. Numerous multicast protocols have been proposed, and most of them assumed that the network entities will relay the multicast packets as prescribed by the multicast protocol without any deviation. While this may be true for the case of LAN multicast in which all network entities belong to the same organization, it can not be taken for granted when the multicast datagrams are routed through different IP networks (called autonomous systems (ASs) in some places). Although multicast benefits the whole system by saving bandwidth and resource, it is dubious that multicast will also bring benefit to every individual AS who relays packets. Thus, it is more reasonable to assume that these ASs, probably owned by different organizations or users,

[‡]Department of Computer Science, University of North Carolina at Charlotte. Email: ywang32@uncc.edu are *selfish*: they aim to maximize their own benefits instead of faithfully conforming to the prescribed multicast protocols. A network composed of selfish ASs is generally known as a *non-cooperative network*. In this paper, we would like to use the terminology "agent" instead of AS because it reflects the selfish nature of the AS.

Nisan and Ronen [2] studied the unicast routing problem in non-cooperative networks and introduced the idea of algorithmic mechanism design. They proposed to give the agents some *proper* payments to ensure that every agent conforms to the prescribed protocol regardless of other agents' behavior, which is known as *truthful* or *strategyproof*. They designed the payment for unicast by using the VCG mechanism [3], [4], [5], which is considered as one of the most positive results in mechanism design. Unfortunately, VCG mechanism has its own drawback. For multicast, if we want to apply the VCG mechanism, we have to find the minimum cost multicast tree, which is known to be NP-Hard for both link weighted networks [6], [7] and node weighted networks [8], [9]. If we insist on applying the VCG mechanism to a multicast topology that does not have the minimum cost, VCG mechanism is no longer truthful [10]. Thus, some payment schemes other than VCG mechanism should be designed for multicast. Recently, several non-VCG truthful payment schemes were proposed in [10] for several commonly used multicast trees. In this paper, instead of focusing on a specific multicast structure, we study whether it is possible to transform a multicast protocol using any given multicast structure to a truthful multicast protocol, and if possible, how to design such truthful multicast protocol.

Designing a truthful payment scheme is not the whole story for many practical applications. A natural question to be answered is who will be charged for the payments to the relay agents. A simple solution is that the organization to which the receivers belong pays [10]. However, this solution is not panacea. In many applications such as video streaming, each individual receiver often has to pay for receiving the data. How to charge the receivers for multicast transmission has been studied extensively in literatures [11], [12], [13], [14], [15], [16]. In most of their models, they assumed that 1) every receiver has a valuation for receiving the data and the receiver is selfish, 2) all relay agents are cooperative and will reveal their true costs, and 3) the multicast tree is fixed as the union of the shortest paths from the source to receivers. In a sharp contrast, we take the selfish behavior of the relay agents into account in this paper. Thus, we model the network differently by assuming that 1) the relay agents are selfish and rational, 2) the receivers always receive the data and pay what they "should" pay in a fair way, and 3) the multicast

^{*}Department of Computer Science, Illinois Institute of Technology, Chicago, IL. Emails: wangwei4@iit.edu, xli@cs.iit.edu. The work is partially supported by NSF CCR-0311174.

[†]Department of Computer Science, Hong Kong Baptist University, Hong Kong. Email: sunz@comp.hkbu.edu.hk

topology could be any structure, including trees and meshes. To the best of our knowledge, this is the *first* paper to consider multicast pricing when the relay agents are non-cooperative. We also show the hardness when both the receivers and the relay agents are selfish and rational, and each receiver has a privately known valuation.

The main contributions of this paper are two-folded. First, we present a general framework to decide whether it is possible, and how, if possible, to transform an existing multicast protocol to a truthful one. We then show how the payments to the relay agents are shared *fairly* among the receivers. As running examples, we show how to design truthful multicast protocols for some commonly used Inter-AS multicast protocols. We also conduct extensive simulations to study the relation between the payment and the cost of the multicast structure. Our simulations show that by only overpaying a small amount to the relay agents, each relay agent will declare its true cost out of its own interest to maximize its profit.

The rest of the paper is organized as follows. We introduce some preliminaries, related works, our communication model, and the problems to be solved in Section II. In Section III, we discuss the existence of the truthful payment and how to compute it based on a given multicast structure. We show how to design truthful multicast protocols for the Inter-AS multicast protocol based on source-based tree in Section IV and sharedbased tree in Section V. Alternative models and some other issues for truthful multicast are discussed in Section VI. We also study how to charge selfish receivers with privately known valuations. The performance study of our proposed truthful source-based multicast protocol is presented in Section VII. We conclude our paper in Section VIII.

II. TECHNICAL PRELIMINARIES

A. Algorithmic Mechanism Design

In a standard model of algorithmic mechanism design, there are n agents $\{1, 2, \dots, n\}$. Each agent $i \in \{1, \dots, n\}$ has some private information t_i , called its type, e.g., its cost to forward a packet in a network environment. All agents' types define a profile $t = (t_1, t_2, \dots, t_n)$. Each agent *i* declares a valid type τ_i , which may be different from its actual type t_i , and all agents' strategies define a declared type vector $\tau = (\tau_1, \cdots, \tau_n)$. A mechanism $M = (\mathcal{O}, \mathcal{P})$ is composed of two parts: an allocation method O that maps a declared type vector τ to an output o, and a payment scheme \mathcal{P} that decides the monetary payment $p_i = \mathcal{P}_i(\tau)$ for every agent *i*. Each agent i has a valuation function $w_i(t_i, o)$ that expresses its preference over different outcomes. Agent i's utility (also called *profit*) is $u_i(t_i, o) = w_i(t_i, o) + p_i$. An agent i is said to be *rational* if it always chooses its strategy τ_i to maximize its utility u_i . Most often, algorithmic mechanism design only focuses on the direct revelation mechanism in which the agents' only strategies are to declare their types.

Let $\tau_{-i} = (\tau_1, \cdots, \tau_{i-1}, \tau_{i+1}, \cdots, \tau_n)$, *i.e.*, the strategies of all other agents except *i* and $\tau | {}^i a = (\tau_1, \tau_2, \cdots, \tau_{i-1}, a, \tau_{i+1}, \cdots, \tau_n)$. In this paper, we are only interested in a mechanism $M = (\mathcal{O}, \mathcal{P})$ that satisfies the following three conditions:

- 1) **Incentive Compatibility (IC)**: For every agent *i* and any τ , $w_i(t_i, \mathcal{O}(\tau^{i}t_i)) + p_i(\tau^{i}t_i) \ge w_i(t_i, \mathcal{O}(\tau)) + p_i(\tau)$.
- 2) Individual Rationality (IR): It is also called Voluntary Participation. Every participating agent *i* must have a non-negative utility, *i.e.*, $w_i(t_i, \mathcal{O}(\tau|^i t_i)) + p_i(\tau|^i t_i) \ge 0$.
- 3) Polynomial Time Computability (PC): $\mathcal{O}(\cdot)$ and $\mathcal{P}(\cdot)$ are computable in polynomial time.

A mechanism is *truthful* if it satisfies both IR and IC. Thus, for every agent i, revealing its true type t_i maximizes its utility regardless of what other agents do.

VCG MECHANISM: A direct revelation mechanism $M = (\mathcal{O}, \mathcal{P})$ belongs to the generalized Vickrey-Clarke-Groves (VCG) mechanism family [3], [4], [5] if (1) there are fixed positive numbers β_i , $i \leq i \leq n$, such that the output $\mathcal{O}(t)$ maximizes the objective function $g(o, t) = \sum_i \beta_i \cdot w_i(t_i, o)$, and (2) the payment to the agent i is $\mathcal{P}_i(t) = \frac{1}{\beta_i} \sum_{j \neq i} \beta_j \cdot w_j(t_j, \mathcal{O}(t)) + h_i(t_{-i})$. Here $h_i()$ is an arbitrary function of t_{-i} and typically $h_i(t_{-i}) = -\frac{1}{\beta_i} \sum_{j \neq i} \beta_j \cdot w_j(t_j, \mathcal{O}(t_{-i}))$. It is proved in [5] that a VCG mechanism is truthful. Under mild assumptions, VCG mechanisms are the only truthful implementations [17] for problems with $g(o, t) = \sum_i \beta_i \cdot w_i(t_i, o)$.

B. Network Model and Problem Statement

In this paper, we focus on the Inter-AS multicasting instead of the Intra-AS routing because Intra-ASs are usually cooperative instead of non-cooperative. Figure 1 (a) shows an example of a multicast network topology with end hosts. Figure 1 (b) shows the corresponding Inter-AS multicasting topology. Here, we model the Inter-AS network topology

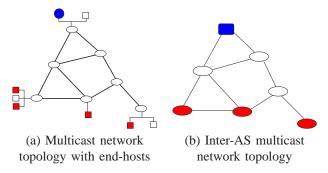


Fig. 1. The solid circle is the source host and the solid squares are the receiving hosts of the multicast group, while the solid rectangle is the AS attached with the source host and the solid ellipses are the ASs attached with the receiving hosts.

as a graph G = (V, E, c), where $V = \{v_1, \dots, v_n\}$ is the set of ASs, $E = \{e_1, e_2, \dots, e_m\}$ is the set of links between ASs. Usually, in Inter-AS routing, each AS actually is an independent economic decision maker who could choose its strategy for financial advantage in routing decisions. We assume that each AS v_i is an individual agent and it has a *fixed* private cost c_i to transmit a unit size of data in multicast. Thus, every AS is called upon to declare its cost to the protocol. When the nodes are the selfish agents, we call this network a *node weighted network*. On the other hand, sometimes we need to treat the selfish agents as links in the network, *e.g.*, the multicast datagram is sent from one AS to another AS by using application layer tunneling through other ASs. If links are agents, the network is modeled as a *link weighted network*. Most of our general techniques in Sections III, IV are not specific to one model, and thus can be applied to both models.

Given a set of multicast group members, in this paper, the receivers are the ASs with some attached group members instead of the actual end hosts who are the multicast group members. For the convenience of our analysis, we assume that s is the source AS in one specific multicast and the size of the data is normalized to 1. We also assume that agents in the network will not *collude* to improve their profits together. In order to prevent monopoly, we assume that the network is biconnected. Given a source node $s = q_0$ and a set of multicast receivers $R = \{q_1, q_2, \cdots, q_r\} \subset V$, we need to design a multicast protocol that

- 1) constructs a topology (a tree, a mesh, a ring, etc.) that spans the source and all receivers;
- calculates a payment for each relay AS according to a *payment scheme* that is truthful;
- 3) charges each receiver according to a *payment sharing scheme* that is *fair*. We will formally define what is fair in subsection III-C.

One thing we should highlight here is that, instead of reinventing the wheel by designing some new multicast structures, we focus on how we can design a truthful payment scheme for a certain existing multicast protocols to ensure that they work correctly even in non-cooperative networks. Based on the truthful payment scheme we designed, we further study *how* we charge the receivers in a fair way.

Given a structure $H \subseteq G$, we use $\mathbf{c}(H)$ to denote the total cost of all agents in H. If we change the cost of any AS i to c'_i , we denote the new network as $G' = (V, E, c|^i c'_i)$, or simply $c|^i c'_i$. If we remove one AS v_i from the network, we denote it as $c|^i \infty$. Hereafter, we use $\mathsf{LCP}(u, v, c)$ to denote the least cost path from node u to node v in a network G = (V, E, c). For simplicity of notations, we will use only the cost vector cto denote the network G = (V, E, c) if no confusion is caused. We let c_{-i} denote the costs of all ASs other than AS v_i .

C. Related Work

Routing has been part of algorithmic mechanism design from the very beginning. Nisan and Ronen [18] provided a polynomial-time truthful mechanism for unicast routing in a centralized computational model. Each link e_i of the network is an agent and has a private cost t_i of sending a message. Their mechanism is essentially a VCG mechanism. The result in [18] is extended in [19] to deal with unicast problem for all pairs of agents. They assume that there is a traffic demand $T_{i,j}$ from an agent i to an agent j. They also gave a distributed method to compute the payment. Anderegg and Eidenbenz [20] recently proposed a similar routing protocol based on VCG mechanism for wireless ad hoc networks. By assuming that each node is a selfish agent, Wang and Li [21] proposed an asymptotically optimum centralized method to compute the payment for unicast and showed that no truthful mechanism can prevent collusion among any pair of agents.

For multicast, Feigenbaum *et al.* [15] assumed that there is a universal tree T spanning all receivers and for every subset

 $Q \subseteq R$ of receivers, the tree T(Q) spanning Q is merely the subtree of T that spans Q. They also assumed that the link costs are publicly known and each receiver q_i has a privately known valuation w_i on receiving the data. It will report a number w'_i , which is the amount of money it is willing to pay to receive the data, and w'_i may be different from w_i . They studied how to select a subset $Q \subset R$ of receivers according to some criteria and proposed to use *Shapely value* and *marginal cost* to share the link cost of the multicast tree. Maximizing profit in multicast was studied in [22], [23] ([23] is based on cancelable auction [24]). Sharing the *cost* of the multicast structure among receivers to achieve some fairness was studied in [25], [26], [27], [14], [16], [28]. Wang *et al.* [10] studied how to design truthful multicast protocols for various multicast trees when the nodes or links are selfish.

III. CHARACTERIZATION OF TRUTHFUL MULTICAST ROUTING

Several multicast topologies have been proposed and used in practice and more topologies are expected to appear in the near future. It will be difficult, if not impossible, to design a truthful multicast mechanism for each of these topologies individually. Thus, instead of studying some specific multicast topologies, we focus on designing a general framework to solve the problem whether there is, and how to design if it exits, a truthful mechanism for a given multicast topology. We also consider how to charge the receivers to cover the payments to the selfish relay agents.

Intuitively, we may still want to use the VCG payment schemes for these multicast topologies. Notice that an allocation method of a VCG mechanism is required to maximize the total valuations of agents. This makes the mechanism computationally intractable in many cases, *e.g.*, multicast. Notice that replacing the optimal solution with non-optimal approximation usually leads to untruthful mechanisms [10]. Thus a mechanism other than VCG is needed when we cannot find the optimal solution or the objective is not to maximize the total valuation of the agents. This paper presents the *first general* framework to design truthful mechanisms for multicast in case we cannot find a structure with the minimum total cost.

A. Existence of Truthful Payment Mechanism

Before we design some truthful payment scheme for a given multicast topology, we should decide whether such payment scheme exists or not. The following definition and theorem will present a sufficient and necessary condition for the existence of the truthful payment scheme.

Definition 1: A method \mathcal{O} constructing a multicast topology satisfies the **monotone non-increasing property** (MNP) if for every agent *i* and fixed c_{-i} , the following condition is satisfied: if agent *i* is selected as a relay agent with cost c_{i_2} , then it is also selected with a cost $c_{i_1} < c_{i_2}$.

Obviously, the above condition is equivalent to the following condition: there exists a threshold value $\kappa_i(\mathcal{O}, c_{-i})$ such that if *i* is selected as a relay agent, then its cost is at most $\kappa_i(\mathcal{O}, c_{-i})$. For convenience, we use $\mathcal{O}_i(c) = 1$ (respectively, 0) to denote that agent i is selected (respectively, not selected) to the multicast topology when the cost vector is c.

Theorem 1: Given a method \mathcal{O} constructing a multicast topology, there exists a payment \mathcal{P} such that $M = (\mathcal{O}, \mathcal{P})$ is truthful if and only if \mathcal{O} satisfies the MNP.

Proof: We first prove that if there exists a truthful payment \mathcal{P} based on \mathcal{O} then \mathcal{O} satisfies the MNP. For the sake of contradiction, we assume that there is a truthful payment scheme \mathcal{P} and \mathcal{O} that does not satisfy MNP. From the definition of MNP, there exists an agent i and two cost vectors $c|^i c_{i_1}$ and $c|^i c_{i_2}$ with $c_{i_1} < c_{i_2}$ such that $\mathcal{O}_i(c|^i c_{i_2}) = 1$ and $\mathcal{O}_i(c|^i c_{i_1}) = 0$. Let $\mathcal{P}_i(c|^i c_{i_1}) = p_i^0$ and $\mathcal{P}_i(c|^i c_{i_2}) = p_i^1$.

Consider a network with a cost vector $c|^i c_{i_1}$, the utility for the agent *i* when it reveals its true cost is $u_i(c_{i_1}) = p_i^0$. When agent *i* lies its cost to c_{i_2} , its utility becomes $p_i^1 - c_{i_1}$. Since payment scheme \mathcal{P} is truthful, we have $p_i^0 \ge p_i^1 - c_{i_1}$.

Similarly we consider another network with a cost vector $c|^i c_{i_2}$. Agent *i*'s utility is $p_i^1 - c_{i_2}$ when it reveals its true cost. Similarly, if it lies its cost to c_{i_1} , its utility is p_i^0 . Since payment scheme \mathcal{P} is truthful, $p_i^0 \leq p_i^1 - c_{i_2}$.

Thus, we have $p_i^1 - c_{i_2} \ge p_i^0 \ge p_i^{-1} - c_{i_1}$, which implies that $c_{i_1} \ge c_{i_2}$. It is a contradiction to $c_{i_1} < c_{i_2}$.

We then prove that if \mathcal{O} satisfies MNP, there exists a truthful mechanism $M = (\mathcal{O}, \mathcal{P})$. We prove it by constructing the following payment scheme \mathcal{P} .

Algorithm 1 Payment Scheme \mathcal{P}	Algorithm 1	1 Payment	Scheme \mathcal{P}
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- 1: For any agent *i* not selected to relay, its payment is 0.
- 2: For any agent *i* selected to relay, its payment is $\kappa_i(\mathcal{O}, c_{-i})$.

From the definition of MNP, the payment scheme \mathcal{P} satisfies IR. Thus we only need to prove that the payment scheme \mathcal{P} satisfies IC. We prove it by cases.

Case 1: Agent *i* lies its cost upward to $\overline{c_i}$ or downward to $\underline{c_i}$, but it does not change the output whether agent *i* is selected or not. Notice that, for a fixed c_{-i} , when the output of agent *i* does not change, its payment is the same. Thus, agent *i*'s utility remains the same, implying that agent *i* does not have incentive to lie in this case.

Case 2: Agent *i* is selected when it reveals its actual cost c_i , and it lies its cost upward to $\overline{c_i}$ such that it is not selected. From the property of MNP, we know $c_i \leq \kappa_i(\mathcal{O}, c_{-i})$. This ensures that agent *i* gets non-negative utility when it reveals its actual cost c_i . When *i* lies its cost to $\overline{c_i}$, it gets zero payment and zero utility. Therefore, agent *i* won't lie in this case.

Case 3: Agent *i* is not selected when it reveals its actual cost c_i , and it lies its cost downward to $\overline{c_i}$ such that it is selected. Similarly, we have $c_i \ge \kappa_i(\mathcal{O}, c_{-i})$, which implies that agent *i* gets a non-positive utility. Comparing with the zero utility when agent *i* reveals its true cost, agent *i* also has no incentive to lie in this case.

Actually, if we require that relay agents who are not selected should receive zero payment, our payment scheme illustrated by Algorithm 1 is the *only* truthful payment scheme.

B. Rules to Find Truthful Payment Scheme

Given a multicast structure satisfying MNP, it seems quite simple to find a truthful payment scheme by applying Algorithm 1. However, sometimes the process to find the threshold value in Algorithm 1 is far more complicated. Instead of trying to propose a unified approach that can find the threshold value for all multicast topologies satisfying MNP, we present some useful techniques to find the threshold value under certain circumstances. Our general approach works as follows. First, given an allocation method \mathcal{O} that constructs a multicast structure, we decompose it into several simpler allocation methods. We then find the threshold value for each of the decomposed methods. Finally, we calculate the original threshold value by combining the threshold values for those decomposed methods. In the following, we present several useful decomposition techniques.

1) Simple Combination: Given a multicast method \mathcal{O} , let $\kappa(\mathcal{O}, c)$ denote the *n*-tuple vector

$$(\kappa_1(\mathcal{O}, c_{-1}), \kappa_2(\mathcal{O}, c_{-2}), \cdots, \kappa_n(\mathcal{O}, c_{-n})).$$

Here, $\kappa_i(\mathcal{O}, c_{-i})$ is the threshold value for agent *i* when the multicast topology is constructed by \mathcal{O} and the costs c_{-i} of all other agents are fixed. We then present a simple but useful technique to find the threshold value.

Theorem 2: Given g allocation methods $\mathcal{O}^1, \dots, \mathcal{O}^g$ each satisfying MNP, and the threshold value $\kappa(\mathcal{O}^i, c)$ for each \mathcal{O}^i , the method $\mathcal{O}(c) = \mathcal{O}^1(c) \bigvee \mathcal{O}^2(c) \bigvee \dots \bigvee \mathcal{O}^g(c)$ satisfies MNP. Moreover, the threshold value for \mathcal{O} is

$$\kappa(\mathcal{O}, c) = \max_{1 \le i \le a} \{\kappa(\mathcal{O}^i, c)\}.$$

The proof of Theorem 2 is straightforward and thus is omitted here. We will show how to use this simple combination technique in Section IV. Notice each individual method \mathcal{O}^i may not construct a multicast tree at all.

2) Round-based Method: Many multicast topologies are constructed in a *round-based* manner: in each round some previously unselected agents are selected, and then the network and the receiver set are updated if necessary. In the following we give a general characterization of a round-based method that constructs a multicast topology.

Algorithm 2 A r	round-based	multicast	method
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1: Set r = 1 and $c^{(1)} = c$ and $Q^{(1)} = R$ initially.

2: repeat

- 3: Let \mathcal{O}^r be a deterministic method that decides in round r which agents will be selected.
- 4: Update the network cost vector and receiver set, *i.e.*, we obtain a new network cost vector $c^{(r+1)}$ and receiver set $Q^{(r+1)}$ according to an *updating rule* U^r :

$$\mathcal{U}^r: \mathcal{O}^r \times [c^r, Q^{(r)}] \to [c^{(r+1)}, Q^{(r+1)}].$$

- 5: until the *desired property* of the multicast topology is met
- 6: Return the union of the selected relay agents in all rounds.

To illustrate the general round-based method, in Algorithm 3 we review a round-based multicast tree construction method [7] that finds a tree whose cost is no more than 2 times that of a minimum cost Steiner tree (MCST) in a link weighted network. We denote the constructed multicast tree as LST, which stands for Link-weighted Steiner Tree.

Algorithm 3 Link weighted multicast structure [7]

1: repeat

- Let d be the vector of costs declared by all agents. 2:
- 3: Find one receiver in the receiver set R, say q_i , that is closest to the source s, *i.e.*, $LCP(s, q_i, d)$ has the lowest cost among the shortest paths from s to all receivers. Connect q_i to the source s using LCP (s, q_i, d) , *i.e.*, all agents on this path are selected.
- 4: Set the cost of every link on this path to 0. Remove q_i from the receiver set R.
- 5: **until** no receiver remains in R

Here, no receiver remains in R corresponds to the desired property of the general round-based method; $LCP(s, q_i, d)$ in round r corresponds to \mathcal{O}^r ; setting costs of links on $LCP(s, q_i, d)$ to 0 and removing q_i from R is the updating rule \mathcal{U}^r . To study whether a general round-based method implies a truthful payment scheme we propose the following definition.

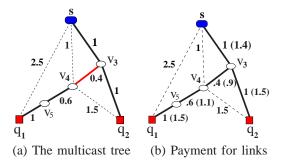
Definition 2: An updating rule \mathcal{U}^r is said to be crossing*independent* if for any agent *i* not selected in round *r*:

- $c_{-i}^{(r+1)}$ and $Q^{(r+1)}$ do not depend on $c_i^{(r)}$. For a fixed $c_{-i}^{(r)}$, if $d_i^{(r)} < c_i^{(r)}$ then $d_i^{(r+1)} < c_i^{(r+1)}$.

Theorem 3: A round-based multicast method O satisfies MNP if, for every round r, method \mathcal{O}^r satisfies MNP and the updating rule \mathcal{U}^r is crossing-independent.

Proof: For an agent *i*, fix the cost c_{-i} of all other agents. We prove that if i is selected when the cost vector is a = $\{c_{-i}, c_i\}$, then it is also selected when the cost vector is b = $\{c_{-i}, c'_i\}$ such that $c'_i < c_i$. Without loss of generality, we assume that i is selected in round r when the cost vector is a. Then when the cost vector is b, if agent i is selected before round r, our claim holds. Otherwise, in round r, $a_{-i}^{(r)} = b_{-i}^{(r)}$ and $a_i^{(r)} > b_i^{(r)}$ since agent i is not selected in the previous rounds. Notice that agent i is selected in round r when the cost vector is $a_i^{(r)}$. Thus, agent *i* is also selected in round *r* when the cost vector is $b_i^{(r)}$ since \mathcal{O}^r satisfies MNP.

In Algorithm 4, we show how to find the threshold value for any selected agent k when the truthful payment scheme exists for a round-based multicast method.



Payment calculation based on LST found by Algorithm 3. Fig. 2.

We use the network in Figure 2 to illustrate how to find the threshold value for link v_3v_4 based on LST. In the first round, v_3v_4 cannot be selected, thus $\ell_1 = 0$. In second round, it is easy to observe that when v_3v_4 's cost is smaller than 0.9, the path $v_3v_4v_5q_1$ is selected and when v_3v_4 's cost is greater Algorithm 4 Computing payment for a selected agent k based on round-based multicast method \mathcal{O}

1: Initially set the cost c_k of k to ∞ and r = 1.

- Find the threshold value for agent k based on \mathcal{O}^r 3: under cost vector $c_{-k}^{(r)}$ and receiver set $Q^{(r)}$. Let $\ell_r =$ $\kappa_k(\mathcal{O}^r, c^r_{-k})$ be the threshold value found. Here we set $\ell_r = 0$ if agent k cannot be selected in this round under any cost.
- Update the cost vector and receiver set to obtain the 4: new cost vector $c^{(r+1)}$ and $Q^{(r+1)}$. Set r = r + 1.
- 5: until the desired property of the multicast topology is met
- 6: Fix c_{-k} and assume x is the payment for agent k. Let $f_i(x)$ be the cost for agent k in round i if the original cost is $c|^k x$. Then x the largest value that satisfies the following inequations: $f_i(x) \leq \ell_i$ for $1 \leq i \leq r$. In other words, the payment to an agent k is the largest possible value it could declare such that it is still selected in some round.

than 0.9, path sq_1 is selected. Thus, the threshold value for v_3v_4 in this round is $\ell_2 = 0.9$. Notice that the updating rule of Algorithm 3 does not change the cost of an unselected agent, *i.e.*, it is crossing-independent and $f_i(x) = x$. Thus, the final threshold value is simply $\max\{\ell_1, \ell_2\} = 0.9$, which is the payment to link v_3v_4 . Similarly, we can find all selected links' threshold values as shown by the numbers in the parenthesis in Figure 2(b). See the conference version [29] for more examples.

C. Fair Payment Sharing Scheme

For a given set of receivers, after we calculate the payment $p_k(d)$ for every relay agent k based on declared costs d, we are ready to study how to share the payments fairly among receivers. Notice that the payment sharing is different from the traditional cost sharing. How to share the multicast cost among the receivers has been studied previously in [26], [12], [15], [11], with the assumption that the costs of relay agents are public and the multicast topology is a fixed tree. Most of the literatures used the Equal Link Split Downstream (ELSD) pricing scheme to charge receivers: the cost of a link is shared equally among all its downstream receivers. As we will show later, if we simply use the ELSD to share the total payment among receivers, it usually is not fair according to some common senses.

Given a set of receivers R, let $\mathcal{P}(R,d) = \sum_k p_k(R,d)$ denote the total payment to all relay agents. For a sharing scheme ξ , let $\xi_i(R, d)$ denote the sharing (or called charge) of a receiver q_i . Let $\xi(R,d) = \sum_{q_i \in R} \xi_i(R,d)$ be the total payment collected from all receivers. We call a sharing scheme ξ reasonable or fair if it satisfies the following criteria.

- 1) **Budget Balance** (BB): The total payment to all agents should be shared by all receivers, *i.e.*, $\mathcal{P}(R, d) = \xi(R, d)$.
- 2) Nonnegative Sharing (NNS): Any receiver q_i 's sharing should not be negative, *i.e.*, $\xi_i(R, d) > 0$.
- 3) **Cross-Monotone** (CM): For any two receiver sets $R_1 \subseteq$ R_2 containing $q_i: \xi_i(R_1, d) \leq \xi_i(R_2, d)$. In other words,

^{2:} repeat

for a given network, receiver *i*'s sharing does not increase when more receivers require service.

 No-Free-Rider (NFR): The sharing ξ_i(R, d) of a receiver q_i ∈ R is at least ¹/_{|R|} of its unicast sharing ξ_i(q_i, d). Thus, the sharing of any receiver will not be too small.

By assuming a universal multicast tree and publicly known link costs, Feigenbaum *et al.* [15] proved that ELSD cost sharing scheme is fair. Unfortunately, the ELSD scheme is not fair if it is used to share the payment.

Lemma 4: ELSD is not a fair payment sharing scheme for payment \mathcal{P} defined based on tree LST.

Proof: We prove it by presenting a counter example using the network shown in Figure 2 (a). When consider only one receiver in LST, we have $\mathcal{P}(q_1, c) = 2.6$ and $\mathcal{P}(q_2, c) = 1.4 + 1.5 = 2.9$. See Figure 3 for illustration. For two receivers

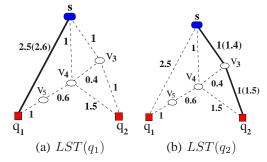


Fig. 3. $LST(q_1)$ and $LST(q_2)$ and their corresponding payment.

 q_1, q_2 , if we use ELSD to share payment, the sharing by q_1 is $\xi_1(\{q_1, q_2\}, c) = \frac{1.4}{2} + 0.9 + 1.1 + 1.5 = 4.2$ which is larger than its sharing $\xi_1(q_1, c) = 2.6$ when q_1 is the only receiver. Thus, ELSD violates the CM property. It implies that ELSD is not a fair sharing scheme for multicast topology LST.

Furthermore, using the same example, we prove that:

Lemma 5: No payment sharing scheme satisfies both CM and BB for the truthful payment scheme based on LST.

Proof: For the sake of contradiction, we assume that a sharing scheme ξ' satisfies both CM and BB. From the property of BB, we have $\xi'_1(q_1, c) = 2.6$, $\xi'_1(q_2, c) = 2.9$ and $\xi'_1(\{q_1, q_2\}, c) + \xi'_2(\{q_1, q_2\}, c) = 6.4$. From CM, we have $\xi'_1(\{q_1, q_2\}, c) \leq \xi'_1(q_1, c) = 2.6$ and $\xi'_2(\{q_1, q_2\}, c) \leq \xi'_2(q_2, c) = 2.9$. Combining these two inequalities, we obtain $6.4 = \xi'_1(\{q_1, q_2\}, c) + \xi'_2(\{q_1, q_2\}, c) \leq 2.9 + 2.6 = 5.5$, which is a contradiction.

Thus, given a certain multicast topology and its corresponding truthful payment scheme, a fair payment sharing scheme may not exist. It is attractive and important to find the necessary and sufficient condition for the existence of a fair payment sharing scheme for a given payment scheme.

IV. TRUTHFUL MULTICAST USING SOURCE-BASED TREE

In this section, we illustrate how to design a truthful multicast protocol with the support of Multiprotocol Extensions for BGP-4 [30]. We treat every AS i in the network as a node in the graph, and assume that it has a fix cost c_i to relay a unit size of datagram for a specific multicast regardless of its downstream links. This could be because that the multicast ASs adopt the Reverse Path Broadcasting (RPB) scheme or the cost of sending extra copies to other interfaces is negligible. Thus, the network is modeled as a node weighted graph. All our results presented hereafter also apply to the case when the network is modeled as a link weighted graph. We focus on the *source-based tree* in this section and discuss the *shared-based tree* in the next section.

A. Construct Multicast Tree

Before designing a truthful multicast protocol, we review some technical details of MBGP including the multicast tree construction method. Multiprotocol extension for BGP (MBGP) [30] is an extension to the existing Border Gate Way (BGP) protocol [31]. In BGP, every node v_i stores, for each other node v_j , the least cost path (the sequence of ASs traversed) from v_i to v_j . Let D be the diameter of the network, *i.e.*, the maximum number of ASs in an LCP. An AS stores $O(n \cdot D)$ AS numbers. In BGP, to perform Inter-AS multicast routing, we use the BGP infrastructure that was in place for unicast routing. A multicast routing protocol, such as Protocol Independent Multicast (MIP) dense mode, uses the multicast BGP database to perform Reverse Path Forwarding (RPF) lookups for multicast-capable sources.

Thus, given a set of receivers R, the least cost path between the source s and each receiver $q_i \in R$ under the reported cost profile d is already in receiver q_i 's unicast database. The union of all least cost paths between the source and the receivers is called the *least cost path tree*, denoted by LCPT(R, d). Every node that is the part of the multicast tree LCPT has a copy of the tree topology and all datagrams are routed along the tree.

B. Payment Scheme

It was shown in [10] that the direct application of VCG payment scheme on LCPT is not truthful. In other words, a node may have incentives to lie about its cost when VCG payment scheme is used. On the other hand, since LCPT is formed by the union of the least cost paths, by applying Theorem 2, we can show that LCPT satisfies MNP. Thus, there exists a truthful payment scheme and the truthful payment can be found according to Theorem 1. It works as follows.

For each receiver $q_i \in R$, we find the least cost path $\mathsf{LCP}(s, q_i, d)$ from the source s (say q_0) to q_i , and compute an intermediate payment $p_k^{i,0}(d)$ to every node v_k on $\mathsf{LCP}(q_0, q_i, d)$ using the VCG payment scheme for unicast

$$p_k^{i,0}(d) = d_k + \mathbf{c}(\mathsf{LCP}(q_0, q_i, d|^k \infty)) - \mathbf{c}(\mathsf{LCP}(q_0, q_i, d)).$$

The final payment to a node $v_k \in \mathsf{LCPT}$ is

$$p_k(d) = \max_{q_i \in R} p_k^{i,0}(d)$$
(1)

The payment to a node is zero if it is not on LCPT.

C. Distributed Payment Algorithm

Remember that MBGP is only an extension to the BGP which is used for unicast. Usually the unicast is a dominant activity in the Inter-AS routing instead of multicast. Thus, we assume that each AS already implements a truthful payment scheme based on VCG for unicast. In [19], Feigenbaum *et al.*

proposed a distributed algorithm to compute the payment $p_k^{i,j}$ for every pair of nodes v_i , v_j and every node v_k on the least cost path $LCP(v_i, v_i, d)$. Their approach is an extension to the existing BGP routing and converges to a stable state after D_{-k} rounds, where D_{-k} is the maximum possible diameter of graph G after removing any node k from the network. In their approach, at every node v_i , they only store the length of the path $LCP(v_i, v_j, d)$ for every node v_j , which requires an extra O(n) space. However, in our approach, we require that every node v_i stores all the payments $p_k^{i,j}$ for every possible source node v_j and every node v_k on path LCP (v_i, v_j, d) . Our approach requires an extra space size of $O(\alpha \cdot D)$ for every AS, where α is the number of possible source node and D is the diameter of the network. Clearly, it avoids the recalculation of every $p_k^{i,j}$ when some nodes' costs are updated. The following algorithm summarize the distributed payment computing for multicast when $s = q_0$ is the source node.

Algorithm 5 Distributed payment computing

- 1: for every receiver q_i do
- Prepare a control datagram composed of the payment 2: $p_k^{i,0}$ for every node v_k on path LCP (q_0, q_i, d) . Sends datagram containing the payment information to
- 3: its parent in the tree LCPT.
- 4: Upon receiving a packet containing the payment from its child which is originated from receiver q_i , node v_k extracts the payment $p_k^{i,0}$ and sends the datagram containing all remaining payment information to its parent if it exists.
- 5: When a node v_k receives $p_k^{i,0}$ from every downstream receiver q_i , it computes the maximum of them as its final payment.

Now we discuss the overhead of our distributed multicast payment computation in terms of both communication messages and memory space used in the AS. It is not difficult to observe that every node receives at most r packets of size O(D) where r is the number of the receivers and D is the diameter of the network. For every node v_i , it only needs to store for each multicast session S the final payment p_S , which is negligible. However, sometime in order to achieve a high efficiency, node v_k may cache every intermediate payment $p_k^{i,0}$. Even in this case, it only needs an extra O(r) space which is much smaller than the space needed for one session of multicast in a cooperative network. Overall, the overhead needed to calculate the payment is small both in terms of space and network message.

D. Payment Sharing Among Receivers

In literature, the Shapely value [32] is one of the most commonly used sharing schemes to achieve BB and CM. If the total payment $\tilde{\mathcal{P}}(R,d)$ satisfies non-decreasing and submodular property, then the Shapely value minimizes the worst-case network welfare loss among all sharing schemes that achieve BB and CM. Here, a payment \mathcal{P} is submodular if $\forall R_1 \subseteq Q$ and $R_2 \subseteq Q$, $\mathcal{P}(R_1, d) + \mathcal{P}(R_2, d) \geq \mathcal{P}(R_1 \cup R_2, d) + \mathcal{P}(R_1 \cap R_2, d)$. The network welfare is defined as the total valuation of all selected receivers minus the cost of the network providing service. If we apply Shapely value to multicast payment sharing, we obtain the following formula

$$\xi_i(R,d) = \sum_{T \subseteq R-q_i} \frac{|T|!(|R| - |T| - 1)!}{|R|!} (\mathcal{P}(T \cup \{q_i\}, d) - \mathcal{P}(T, d))$$

By assuming a fixed multicast tree and publicly known link costs, Feigenbaum et al. [15] proved that ELSD sharing scheme is the Shapely Value. Intuitively, one may want to use ELSD as the payment sharing scheme. Unfortunately, we will show by example that ELSD is not fair when coupled with LCPT. Consider a network shown by Figure 4(a). There are two receivers q_1, q_2 . Tree LCPT (q_1, d) is shown in Figure 4(b).

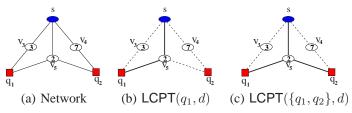


Fig. 4. ELSD sharing scheme is not fair for payment based on LCPT.

The total payment to nodes on $LCPT(q_1, d)$ is 3. Consider $LCPT(\{q_1, q_2\}, d)$ illustrated by Figure 4(c). The payment to only relay node v_5 is 7. If we apply ELSD to share this payment, the shared payment of receiver q_1 is $\frac{7}{2} = 3.5$ when the receiver set is $\{q_1, q_2\}$. Notice that the payment sharing by q_1 is only 3 when it is the only receiver. Thus, ELSD violates the CM property here. Therefore some fair sharing scheme other than ELSD should be designed. We can use Shapely value due to the following lemma.

Lemma 6: The total payment $\mathcal{P}(R,d)$ for tree LCPT, is nondecreasing and submodular with respect to receiver set R.

Please see the appendix (Section IX) for the proof of the lemma. Consequently, we obtain a sharing scheme satisfying CM and BB by applying Shapely value. However, for any receiver $q_i \in R$, there are $2^{|R|-1}$ subsets in $R - q_i$. Thus, simply applying Shapely value directly is computational intractable when the number of receivers is large. Therefore, we present another interpretation of the sharing scheme that can be computed efficiently. The basic idea is that a receiver should only pay a proportion of the payment that is due to its existence. Roughly speaking, our payment sharing scheme works as follows. Notice that a final payment to a node k is the maximum of payments p_k^i by all receivers. Since different receivers may have different values of payment to agent k, the final payment \mathcal{P}_k should be shared proportionally to their values, not equally among them (as what we do for cost sharing). Figure 5 illustrates the payment sharing scheme that follows. For any node v_k , let $R(v_k)$ be the set of downstream receivers of v_k . Without loss of generality, we assume that $R(v_k) = \{q_{\sigma_1}, q_{\sigma_2}, \cdots, q_{\sigma_{|R(v_k)|}}\}$ such that $0 \le p_k^{\sigma_1} \le p_k^{\sigma_2} \le \cdots \le p_k^{\sigma_{|R(v_k)|}}$, *i.e.*, $p_k = p_k^{\sigma_{|R(v_k)|}}$. We then divide the payment p_k into $|R(v_k)|$ portions: $p_k^{\sigma_1}$, $p_k^{\sigma_2} - p_k^{\sigma_1}$, \cdots , $p_k^{\sigma_{i-1}} - p_k^{\sigma_{i-1}}$, \cdots , $p_k^{\sigma_{|R(v_k)|}} - p_k^{\sigma_{|R(v_k)|-1}}$. Each portion $p_k^{\sigma_i} - p_k^{\sigma_{i-1}}$ is then equally shared among the last $|R(v_k)| - i + 1$ receivers, which have the largest $|R(v_k)| - i + 1$ payments to

We first illustrate how to calculate the payment sharing by

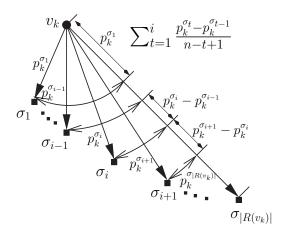


Fig. 5. Share the payment to service providers among receivers fairly.

Algorithm 6 Fair payment sharing scheme for LCPT.

1: for each node $v_k \in \mathsf{LCPT}(R, d)$ do

- 2: Let $R(v_k)$ be the set of downstream receivers of v_k , *i.e.*, $p_k(d) = \max_{q_i \in R(v_k)} p_k^i(d) = \max_{q_i \in R} p_k^i(d)$.
- 3: Sort the receivers in $R(v_k)$ according to $p_k^i(d)$ in an ascending order. If two or more receivers have the same value, the receiver with smaller ID ranks first. Let $\sigma = \{\sigma_0, \sigma_1, \cdots, \sigma_{|R(v_k)|}\}$ be the ranking. Here, we add a dummy payment $p_{k}^{\sigma_0}(d) = 0$ to ranking σ .
- 4: For a receiver not in $R(v_k)$, its sharing of the payment $p_k(d)$ of node v_k is 0.
- 5: For a receiver $q_{\sigma_a} \in R(v_k)$, its sharing of the payment $p_k(d)$ to node v_k is:

$$f_{\sigma_a}^k(R,d) = \sum_{x=1}^a \frac{p_k^{\sigma_x}(d) - p_k^{\sigma_{x-1}}(d)}{|R(v_k)| - x + 1}$$
(2)

In other word, for two receivers q_{σ_x} , $q_{\sigma_{x+1}}$ who are consecutive in ranking σ , the difference $p_k^{\sigma_{x+1}}(d) - p_k^{\sigma_x}(d)$ is shared by all receivers who rank after $q_{\sigma_{x-1}}$.

 P_k (a) is singled by an receiver sine rank after $q_{\sigma_{x-1}}$. 6: The total charge for receiver q_i in LCPT is

$$\xi_i(R,d) = \sum_{v_k \in \mathsf{LCPT}(R,d)} f_i^k(R,d) \tag{3}$$

receiver q_1 using Algorithm 6 for a network represented by Figure 4. For node v_5 , the two intermediate payments are $p_{v_5}^1 = 3$ and $p_{v_5}^2 = 7$. First, we obtain a rank of these receivers based on the intermediate payments of $\{q_1, q_2\}$. Then $p_{v_5}^1 = 3$ is equally split between q_1 and q_2 and $p_{v_5}^2 - p_{v_5}^1 = 4$ is charged to q_2 alone. Thus, receiver q_1 is charged 3/2 = 1.5and receiver q_2 is charged 1.5+4=5.5 in LCPT($\{q_1, q_2\}, d$). Here, q_1 's sharing is smaller than the sharing 3 when q_1 is the only receiver. This shows that the payment sharing scheme described by Algorithm 6 is fair for this specific network. The following theorem shows that our sharing scheme is indeed the Shapely value.

Theorem 7: Our sharing scheme defined by Algorithm 6 is the Shapely value.

Refer to appendix (Section IX) for the proof of the theorem. Recall that when applying Shapely value to a payment satisfying submodular and non-increasing property, the resulting sharing scheme satisfies BB, CM, NNS and NFR. Thus, we have the following theorem directly.

Theorem 8: The sharing scheme defined in Algorithm 6 for LCPT satisfies NNS, CM, NFR and BB.

E. Distributed Computing of Payment-Sharing

In practice, we may need to implement a distributed payment sharing scheme. In the following, we present a distributed algorithm that implements our payment sharing scheme. It requires at most O(r) space for each agent and with $O(r \cdot h)$ total messages, where h is the height of LCPT.

In our distributed algorithm, for any node $v_k \in \mathsf{LCPT}(R, d)$, we not only need its final payment $p_k(d)$, but also need the intermediate payment $p_k^j(d)$ for every downstream receiver q_j . We assume that this is already available through our distributed payment computing scheme (see Algorithm 5). In our distributed charge scheme, at every node v_k , we use $\vartheta_k[i]$ to store the sum of the charge of v_k 's upstream nodes to the receiver q_i . Our distributed payment sharing scheme is implemented in a top-down fashion from the source to all receivers. It is easy to show that Algorithm 7 indeed computes the payment sharing of each receiver correctly.

Algorithm 7 Distributed payment sharing scheme

- 1: Initially, the source node s sends all its children in LCPT a r-dimensional vector $\vartheta = 0$ for all receivers.
- Every node v_k in LCPT(R, d), upon receiving a sharing vector θ̃ from its parent, updates the charge for each of its downstream receivers q_i as θ_k[i] = θ̃[i] + fⁱ_k(R(v_k)). Here, fⁱ_k(R(v_k)) is calculated according to Algorithm 6.
- 3: if node v_k has at least one downstream receiver then
- 4: for every children node v_j , it constructs a charge vector

$$\vartheta_j = (\vartheta[i_1], \vartheta[i_2], \cdots, \vartheta[i_{|R(v_j)|}])$$

Here, the charge $\vartheta[i_t]$, $1 \le t \le |R(v_j)|$, is for receiver q_{i_t} who is a downstream receiver of node v_j . It then sends vector ϑ_j to node v_j .

5: Every receiver q_i will finally receive a charge $\vartheta[i]$ which is equal to $\xi_i(R, d)$ defined in Equation (3).

V. TRUTHFUL MULTICAST USING SHARED-BASED TREE

In section IV, we discussed how to design a truthful multicast protocol using MBGP based on a source-based tree LCPT. However, in practice, Inter-AS multicast usually uses a shared-based tree (SBT) instead due to the following reasons:

- Multicast routing protocols (such as MOSPF, DVMRP and PIM-SM) using a source-based tree are suitable for LAN networks while multicast routing protocols (such as PIM-DM and CBT) using a shared-based tree are more suitable for networks composed of different ASs;
- The shared-based tree is more scalable than the sourcebased tree for applications in which every group member could act as a source.

Furthermore, we can show that the size of extra space needed to support the multicast payment calculation could be reduced significantly. Here, we use the PIM-DM as the routing protocol and the AS should also support MBGP in order to conduct multicast.

We first review the multicast tree construction method by the PIM-DM multicast protocol. For a specific multicast group, the PIM-DM protocol specifies a Rendezvous Point (RP) and the RP maintains a RP-tree, which is usually a least cost path tree that spans all the group members. When any group member wants to send data to the group, it first encapsulates each data packet in a Register message and sends it by unicast to the RP for that group. The RP decapsulates the register messages and forwards the enclosed data packet to downstream group members on the shared RP-tree. Upon receiving data packet from its upstream AS, each intermediate AS further forwards data packets to its downstream ASs. Thus, we can treat the multicast based on a shared-based tree as two separate activities: a unicast from the source to RP, and a multicast with RP as the virtual source node.

We then discuss how to compute the payment to each relay agent and share these payments among receivers. Let $p_k^R(d)$ denote the payment to a relay node $v_k \in \mathsf{LCPT}(R,d)$ according to our truthful payment scheme (see formula (1)). Algorithm 8 presents our truthful payment scheme for multicast based on a shared-based tree.

Algorithm 8 Truthful payment scheme for SBT

- 1: Assume that $s = q_0$ is the RP for a multicast group; and q_i is the source node for a specific multicast session.
- 2: Let d be the cost vector declared by all relay nodes.
- 3: Set the receiver set Q as $R \setminus q_i$.
- 4: Compute the payment $p_k^Q(d)$ for every node v_k on the tree LCPT(Q, d) rooted at RP s and spanning all receivers Q. Set $p_k^Q(d) = 0$ for other nodes v_k . 5: Calculate the payment $p_k^{i,0}(d)$ for every node v_k on path
- $LCP(q_i, q_0, d)$. Set $p_k^{i,0}(d) = 0$ otherwise.
- 6: **for** each node v_k **do** 7: $p_k(d) = p_k^Q(d) + p_k^{i,0}(d)$.

Theorem 9: The payment scheme defined by Algorithm 8 is truthful.

The proof of Theorem 9 is straightforward and thus is omitted. A distributed payment computing protocol similar to Algorithm 5 can be easily designed and thus is omitted here. We then discuss how to share the payments among receivers in Algorithm 9.

Theorem 10: The payment sharing scheme defined in Algorithm 9 is fair, *i.e.*, it satisfies NNS, CM, NFR and BB.

Both the proof of the correctness of the above method and distributing payment-sharing computing are similar to the source-based tree case, thus are omitted here. Here, we do not consider the source q_i as a receiver, which implies that q_i does not share any payment. If q_i should also be treated as a receiver and share the payment in certain circumstances, we just need to modify the receiver set Q = R instead of $Q = R \setminus q_i$ in Line 1 of Algorithm 9.

Algorithm 9 Fair payment sharing scheme for SBT

- 1: Set the receiver set $Q = R \setminus q_i$.
- 2: Share the payment incurred by unicast between q_i and RP equally among all receivers Q. The payment shared by receiver q_k is denoted as $\xi_k^{uni}(Q, d)$.
- 3: Share the payment of multicast with source $s = q_0$ and receiver set Q among all receivers according to Algorithm 6. The payment shared by receiver q_k is denoted as $\xi^{mul}_{\iota}(Q,d).$
- 4: The final payment shared by the receive q_k is $\xi_k(Q, d) =$ $\xi_k^{uni}(Q,d) + \xi_k^{mul}(Q,d)$ when q_i is the source.

VI. OTHER MODELS AND OTHER ISSUES

A. Sharing Payment Among Selfish Receivers

So far, each receiver q_i is assumed to pay its fair sharing $\xi_i(R,d)$ computed by our payment sharing Algorithm 6. In practice, each individual receiver may have a maximum valuation indicating how much it is willing to pay to receive the information from the source. A receiver will choose to receive the information if and only if the charge is at most its valuation. Furthermore, a receiver could also be selfish and rational: it will always maximize its profit by manipulating its reported valuation, should it be possible. This makes the multicast design even harder when both the relay agents and the receivers could be selfish. It is well-known that a crossmonotone cost sharing scheme implies a truthful mechanism for selfish receivers [26]. Thus, when each receiver q_i is willing to pay at most ζ_i for the data, we may design a payment-sharing mechanism as follows.

Algorithm	10	Payment	sharing	for	selfish	receivers	R

1: $Q \leftarrow R$.

- 2: repeat
- Construct the tree LCPT spanning Q only, *i.e.*, we prune out the branches of the original LCPT that do not have receivers in Q.
- For each receiver $q_i \in Q$, compute the payment sharing 4: $\xi_i(Q, d)$ based on the declared costs of all relay agents.
- For each receiver $q_i \in Q$, the receiver q_i is removed 5: from Q if $\xi_i(Q,d) > \zeta_i$, *i.e.*, $Q \leftarrow Q - \{q_i\}$ if $\xi_i(Q,d) > \zeta_i.$
- 6: until no receiver is removed in this round
- 7: All remaining receivers $Q \subseteq R$ will receive the multicast data and pay a sharing $\xi_i(Q, d) \leq \zeta_i$.

However, we found out that a selected relay agent may have incentives to lie about its relay cost under payment scheme defined in Algorithm 6. In the following, we show that a relay agent could change the payment sharing of its downstream receivers by either reporting a higher cost or a lower cost.

Figure 6 illustrates such an example of reporting a lower cost. Here the private valuations of receivers q_1 and q_2 are 12 and 17 respectively. The true costs of links are $c(sv_3) = 5$, $c(sv_4) = 3$, $c(v_3q_1) = 5$, $c(v_4q_2) = 5$, and $c(q_1q_2) = 3$. For the sake of simplicity, we assume that all links (except link

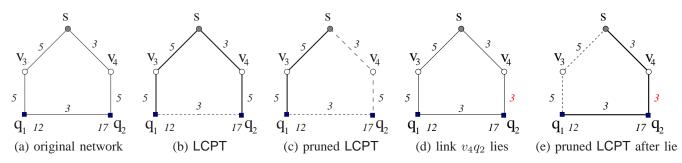


Fig. 6. A relay agent could lie down its cost to improve its utility using Algorithm 6

 v_4q_2) report their costs truthfully in the remaining discussion. Notice when link v_4q_2 truthfully reports its cost, the multicast tree consists of links sv_3 , v_3q_1 , sv_4 and v_4q_2 , as shown by Figure 6 (b). In addition, the payments to selected links are $p_{sv_4} = c(sv_3) + c(v_3q_1) + c(q_1q_2) - c(v_4q_2) = 8$, $p_{v_4q_2} = 10$, $p_{sv_3} = 6$, $p_{v_3q_1} = 6$, and the payments to all other links are 0. Consider two receivers q_1 and q_2 : the payment sharing by receiver q_1 is $p_{sv_3} + p_{v_3q_1} = 12$, which is not larger than its valuation 12; the payment sharing by q_2 is $p_{sv_4} + p_{v_4q_2} = 18$, which is larger than its valuation 17. Consequently, the receiver q_2 will *not* join the multicast (illustrated by Figure 6 (c)). In other words, link v_4q_2 gets payment 0.

Let's see what happens if link v_4q_2 lies its cost down to $3 < c(v_4q_2)$ (illustrated by Figure 6 (d)). Figure 6 (e) shows the multicast tree constructed in this scenario. Notice that when link v_4q_2 reported its cost as 3, the payments to selected links are $p_{sv_4} = 10$, $p_{v_4q_2} = 10$, $p_{q_1q_2} = 4$, and the payments to all other links are 0. It is easy to show that the payment sharings by receivers q_1 and q_2 are 7 and 16 respectively. Then both q_1 and q_2 will join the multicast now. Thus, the link v_4q_2 gets a payment 10 when it lies its cost down to 3.

The above example shows that a relay agent could lie down its cost to improve its utility. It is not difficult to devise an example such that a relay agent could lie up its cost to improve its utility. Due to the space limit, the example is omitted and please refer to our technique report for more details.

B. Other Issues

There are many interesting and important issues that have not been discussed and thus are left for further study. We just list a few here.

Collusion: Throughout this paper, we assume that all agents will not collude together to manipulate the protocol. It is interesting to study what happens when agents can collude and how to find truthful mechanisms that are resistent to collusion. We already knew that there is no truthful multicast protocol that can prevent the collusion between any pair of relay agents, following a previous result [21] for unicast.

Truthful Distributed Implementation: One thing we should notice is that these agents running the distributed algorithms are indeed non-cooperative. How to ensure that they implement the *correct* distributed algorithm we designed also is an important question we have to consider. See [21] for our previous approach on unicast.

Repeated Games: So far we assumed that the session is performed once. A natural question is how we should pay

the relay agents and charge the receivers when the multicast game is to be repeated for several sessions. When we know the private cost of each relay agent, should we just pay each relay agent its declared cost starting from the second session? If we do so, clearly the selfish relay agent will increase its declared cost to improve its later benefit, although this may reduce its benefit in the first session.

Nash Design: One thing we should point out is that algorithmic mechanism design is not the only way to deal with selfishness. A lot of literatures use Nash equilibrium, a state at which no agent can improve its utility by unilaterally deviating from its current strategy when other agents keep their strategies. Since Nash equilibrium has a weak requirement, it often can achieve a wider variety of outcomes. We leave it as future work to design multicast protocols using Nash equilibrium instead of truthful algorithmic mechanism design.

VII. PERFORMANCE STUDY

We conduct extensive simulations to study the performance of truthful multicast routing based on LCPT. For a tree T, let $\mathbf{c}(T)$ be its cost and $\mathcal{P}(T)$ be the total payment to all relay agents. We define the *overpayment ratio* (OR) of T as

$$\varrho(T) = \frac{\mathcal{P}(T)}{c(T)}.$$

Recall that the payment of T is at least its actual cost. Thus, $\varrho(T) \ge 1$ for any tree T. In the worst case, the ratio $\varrho(T)$ could be as large as O(n) for a network of n nodes [33], even for the special case of unicast. Notice there are some other definitions about overpayment ratio in the literature. In [33], the authors proposed to compare the total payment $\mathcal{P}(T)$ with the cost of the new LCPT obtained from the graph $G \setminus T$, *i.e.*, removing T from the original graph G.

In addition to the overpayment ratio, we propose another metric to measure the performance of the truthful multicast based on LCPT. Remember that the payments to relay agents are shared among receivers. Thus, each receiver is more interested in how much extra it is charged to guarantee the truthfulness of agents. Given a tree T for a set of receivers R, let $m_i(R,T)$ be the amount that receiver q_i is charged if agents's costs are publicly known. Notice that $\xi_i(R,d)$ is the amount that receiver q_i is charged if agents are noncooperative. We define the *price-cost-ratio* (PCR) as

$$\eta(q_i, T) = \frac{\xi_i(R, d)}{m_i(R, T)}$$

In our experiment, we generate random networks with n nodes, where n is a parameter. In order to ensure that the network is bi-connected, the average node degree should be greater than $\log n$ with high probability. First, for every node u, we randomly draw a number from $[\alpha \log n, 5\alpha \log n]$ as its degree d_u , where $\alpha \ge 1$ is a parameter. A random graph satisfying this degree requirement is then generated. The cost of each node is then uniformly drawn from distribution [20, 100]. By choosing different parameters, we study what aspects of the network affect the OR and PCR. To compute the probability distribution, we generate 10^4 different networks and compute the number of instances that fall in some specific intervals. For other simulations, given all fixed parameters, we generate 10^3 different network instances and compute the performances accordingly.

A. Effect of Network Size

In this simulation, we fix the parameter α to $\frac{10}{3 \log n}$, which means that node' degrees are drawn from a uniform distribution $\left[\frac{10}{3}, \frac{50}{3}\right]$ with average 20. We also fix the size of receiver set R to 15. We measure the performances of our truthful multicast protocol based on the following four metrics: average overpayment ratio (AOR), maximum overpayment ratio (MOR), average price-cost-ratio (APCR) and maximum pricecost-ratio (MPCR). Figure 7 (a) and (b) plot the distribution of AOR and APCR when the number of nodes is 100 and 250, respectively. Observe that the probability distributions of AOR (also APCR) for different network size are similar. Figure 7 (c) shows that the AOR, MOR and APCR do not change much when the number of network nodes grows from 100 to 500. On the other hand, MPCR fluctuates and is much larger than the other three metrics. Thus, we conclude that the number of nodes does not affect the overpayment ratio and price-costratio in random networks.

B. Effect of Network Density

Since the difference in the network size does not affect the performances of our truthful protocol, we then study other effects by fixing the network size (100 in the results reported here). We specifically study the effect of the network density by changing the node degree parameter α . Figure 8 (a) and (b) show the distributions of AOR and APCR respectively when the node degrees are drawn from two uniform distributions $[\log 100, 5 \log 100]$ and $[2 \log 100, 10 \log 100]$. Figure 8 (c) shows that the AOR, MOR and APCR change when the network density changes. It is interesting to observe that both AOR and APCR first decrease when the network density (i.e., the average node degree) increases from 10 to 32, and then increase slightly when the network density increases from 30 to 42. They both become steady when the network density is greater than 42. It is interesting to analyze this phenomenon theoretically.

C. Performance Comparison with Unicast

In this simulation, we compare the average cost and payment per receiver in multicast based on LCPT with those of unicast. We randomly generate n terminals where n varies from 100 to 500. The degree of each node is randomly drawn from the uniform distribution $[\log n, 5 \log n]$. For a specific network, we average the cost and payment for all receivers.

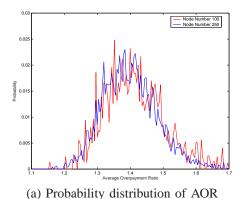
Figure 9 (a) plots the cost and payment for multicast and unicast per receiver when the number of receivers is 15, while Figure 9 (b) shows the results when 10% of nodes are receivers. Observe that the average cost and payment per receiver for multicast based on LCPT are *smaller* than the average cost and payment per receiver for unicast respectively. Furthermore, under most of the cases, the payment per receiver for LCPT payment is even smaller than the cost per receiver for unicast. This ensures us that multicast not only saves the total resources, but also benefits the individual receiver even in *selfish* networks. We then vary the network size among 100, 200, 300, 400, 500 and the number of receivers from 1 to 30. Figure 9 (c) shows the unicast cost (the upper surface) and the LCPT based multicast payment (the lower surface).

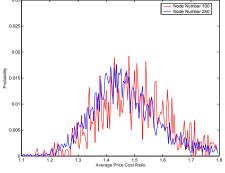
From the results of previous three simulations, we observe that AOR and APCR are both quite small for a random network, and even MOR is smaller than 1.7 generally. Thus, we conclude that the theoretical worst case could happen with only a low probability in a random network.

VIII. CONCLUSION AND FUTURE WORKS

In this paper we discuss how to design truthful payment schemes and payment sharing mechanisms that stimulate cooperation for multicast in a non-cooperative network. We assumed that a group of receivers is willing to pay to receive the data and each possible relay agent has a privately known cost of providing the relay service. In our truthful multicast protocol, each selfish relay agent k is first asked to declare a cost for relaying data for other ASs. In return, it will get a payment based on the reported costs of all relay agents that can provide the service. The objective of every individual relay agent is then to maximize its profit. A multicast protocol is said to be truthful if no speculation and counter speculation happens, *i.e.*, every relay agent will maximize its profit when it truthfully reports its cost.

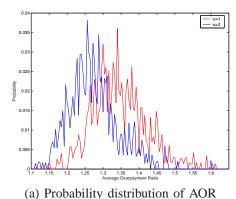
It is well-known that the traditional protocols designed for conforming agents cannot prevent the selfish agents from manipulating their reported costs to increase their benefits. Instead of redesigning the wheel, it is preferred to enhance an existing multicast protocol to deal with selfish agents. In this paper, we specifically gave a general rule to decide whether it is possible and how, if possible, to transform an existing multicast protocol to a truthful multicast protocol. We then showed how the payments to all the relay agents could be shared fairly among all receivers so that it encourages collaboration among receivers. As running examples, we showed how to design a truthful multicast protocol when the least cost path tree or the shared-based tree is used for multicast. We also discussed in detail how to implement this scheme on each selfish node in a distributed manner. Extensive simulations have been conducted to study the relations between payment and cost of the multicast structure when least cost path tree is used. As all truthful mechanisms, the proposed scheme pays

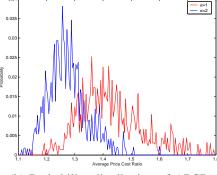




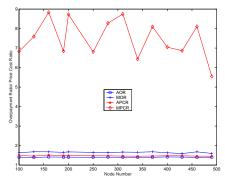
(b) Probability distribution of APCR

Fig. 7. The average overpayment ratio and price cost ratio do not depend on the network density.

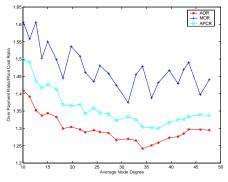




(a) Probability distribution of AOR(b) Probability distribution of APCRFig. 8. The overpayment ratio and price cost ratio depend on the network density.



(c) Average and maximum OR/PCR



(c) Average and maximum OR/PCR

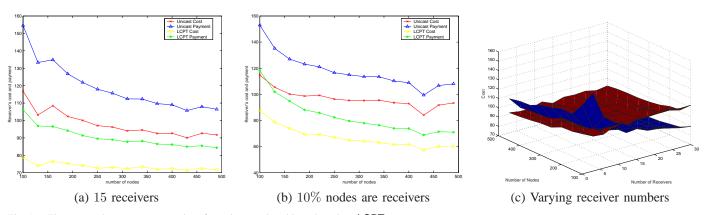


Fig. 9. The cost and payment per receiver for unicast and multicast based on LCPT.

each relay agent more than its declared cost to prevent it from lying. Our extensive simulations showed that the overpayment is small when the cost of each agent is a random value chosen in some range.

As we mentioned early, this paper is the first step to exploring the general network protocol design when relay agents are non-cooperative. There are many interesting and important issues that have not been touched and thus are left for further study.

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IX. APPENDIX

Lemma 6 The total payment $\mathcal{P}(R, d)$ to tree **LCPT** is nondecreasing and submodular with respect to receiver set R.

Proof: By the definition of LCPT, obviously if $R \subset R' \subseteq Q$, then $LCPT(d, R) \subseteq LCPT(d, R')$. Remember the

final payment to a relay agent v_k based on receiver set R is

$$p_k(R,d) = \max_{q_i \in R} p_k^i(d)$$

Observe that $p_k^i(d)$ is not affected by the receiver set R. Thus, for any relay node v_k , if $R \subset R' \subseteq Q$ then $p_k(R,d) \leq p_k(R',d)$. Thus, the total payment to agents on tree LCPT(R,d) is nondecreasing.

We then prove that the total payment $\mathcal{P}(R,d)$ is a submodular function of set R, *i.e.*, $\forall R_1 \subseteq Q$ and $R_2 \subseteq Q$, $\mathcal{P}(R_1,d) + \mathcal{P}(R_2,d) \geq \mathcal{P}(R_1 \cup R_2,d) + \mathcal{P}(R_1 \cap R_2,d)$. Since $\mathcal{P}(R,d) = \sum_{v_k \in R} p_k(R,d)$, it is sufficient to prove that, $\forall k$,

$$p_k(R_1, d) + p_k(R_2, d) \ge p_k(R_1 \cup R_2, d) + p_k(R_1 \cap R_2, d).$$

We prove this by studying two cases whether the agent v_k is on $\mathsf{LCPT}(R_1 \cap R_2, d)$ or not.

Case 1: Agent v_k is not on $\mathsf{LCPT}(R_1 \cap R_2, d)$. Without loss of generality, assume that v_k is on $\mathsf{LCPT}(R_1 \setminus R_2, d)$. Then $p_k(R_2, d) = p_k(R_1 \cap R_2, d) = p_k(R_2 \setminus R_1, d) =$ 0. Consequently, $p_k(R_1 \cup R_2, d) = \max_{q_i \in R_1 \cup R_2} p_k^i(d) =$ $\max_{q_i \in R_1} p_k^i(d) + \max_{q_i \in R_2 \setminus R_1} p_k^i(d) = \max_{q_i \in R_1} p_k^i(d)$. Therefore, in this case we have

$$p_k(R_1, d) + p_k(R_2, d) = p_k(R_1 \cap R_2, d) + p_k(R_1 \cup xR_2, d)$$

Case 2: Agent v_k is on $\mathsf{LCPT}(R_1 \cap R_2, d)$. Without loss of generality, assume $p_k(R_1, d) \leq p_k(R_2, d)$. Thus,

$$p_{k}(R_{1} \cup R_{2}, d) = \max_{q_{i} \in R_{1} \cup R_{2}} p_{k}^{i}(d)$$

$$= \max\{\max_{q_{i} \in R_{2}} p_{k}^{i}(d), \max_{q_{i} \in R_{1} \setminus R_{2}} p_{k}^{i}(d)\}$$

$$\leq \max\{\max_{q_{i} \in R_{2}} p_{k}^{i}(d), \max_{q_{i} \in R_{1}} p_{k}^{i}(d)\}$$

$$= \max_{q_{i} \in R_{2}} p_{k}^{i}(d) = p_{k}(R_{2}, d)$$

On the other hand, we have $p_k(R_2, d) \leq p_k(R_1 \cup R_2, d)$. Thus, $p_k(R_2, d) = p_k(R_1 \cup R_2, d)$. The fact $R_1 \cap R_2 \subseteq R_1$ implies $p_k(R_1 \cap R_2, d) \leq p_k(R_2, d)$. Therefore, we have

$$p_k(R_1, d) + p_k(R_2, d) \ge p_k(R_1 \cap R_2, d) + p_k(R_1 \cup R_2, d)$$

This finishes our proof.

Theorem 7: *Our payment sharing scheme defined in Algorithm* 6 *is the Shapely value.*

Proof: Remember Shapely value for multicast is

$$f_i(R) = \sum_{T \subseteq R \setminus q_i} \frac{|T|!(|R| - |T| - 1)!}{|R|!} [\mathcal{P}(T \cup q_i, d) - \mathcal{P}(T, d)]$$
(4)

In other words, the Shapely value of the receiver q_i is $f_i(R)$ given a set of receivers R. Notice that an agent v_k will contribute to $\mathcal{P}(T \cup q_i, d) - \mathcal{P}(T, d)$ if and only if

- 1) Agent v_k is an upstream agent of receiver q_i .
- 2) $p_k^T(d) < p_k^i(d)$, where $p_k^T(d) = \max_{q_j \in T} p_k^j(d)$.

For fixed T, agent v_k satisfying above two criteria will add non-negative value $p_k^i(d) - p_k^T(d)$ to $\mathcal{P}(T \cup q_i, d) - \mathcal{P}(T, d)$. Let $T_{=x}$ be a receiver set with the highest rank in σ that is exactly x. Similarly, we use $T_{<x}$ to denote a receiver set with the highest rank in σ that is less than x. Let $g_k^i(R)$ be payment to agent v_k that is shared by receiver q_i . Assume that q_i is ranked a in the ranking σ when sorting the payment to agent v_k in a increasing order. Then

$$g_k^i(R) = \sum_{T_{$$

Let γ be the number of receivers who are not the downstream receivers of v_k . Simplifying the first part of the equation, we get

$$\sum_{\substack{T_{

$$= p_k^i(d) \cdot \sum_{\substack{x=0 \\ x=0}}^{\gamma+a-1} \frac{x!(|R|-x-1)!}{|R|!} \cdot \binom{a+\gamma-1}{x}$$

$$= \frac{p_k^i(d)}{|R|-a-\gamma+1} = \frac{p_k^i(d)}{|R(v_k)|-a+1}$$$$

Simplifying the second part of the equation, we get

$$\begin{split} &\sum_{x=0}^{a-1} \sum_{T=x \subseteq R-q_i} \left(\frac{|T_{=x}|!(|R|-|T_{=x}|-1)!}{|R|!} \cdot p_k^{\sigma_x}(d) \right) \\ &= \sum_{x=0}^{a-1} \left(p_k^{\sigma_x}(d) \cdot \sum_{y=0}^{x+\gamma-1} \frac{(y+1)!(|R|-y-2)!}{|R|!} \cdot \binom{x+\gamma-1}{y} \right) \\ &= \sum_{x=1}^{a-1} \frac{p_k^{\sigma_x}(d)}{(|R|-x-\gamma+1) \cdot (|R|-x-\gamma)} \\ &= \sum_{x=1}^{a-1} \frac{p_k^{\sigma_x}(d)}{(|R(v_k)|-x+1) \cdot (|R(v_k)|-x)} \\ &= \sum_{x=1}^{a-1} p_k^{\sigma_x}(d) \cdot \left(\frac{1}{(|R(v_k)|-x)} - \frac{1}{(|R(v_k)|-x+1)} \right) \\ &= \frac{p_k^{\sigma_{a-1}}(d)}{(|R(v_k)|-a+1)} - \sum_{x=1}^{a-1} \frac{p_k^{\sigma_x}(d) - p_k^{\sigma_{x-1}}(d)}{(|R(v_k)|-x+1)} \end{split}$$

Combining the above two equations, then $g_k^i(R)$ equals to

$$\begin{aligned} & \frac{p_k^i(d)}{|R(v_k)| - a + 1} - \left[\frac{p_k^{\sigma_{a-1}}(d)}{(|R(v_k)| - a + 1)} - \sum_{x=1}^{a-1} \frac{p_k^{\sigma_x}(d) - p_k^{\sigma_{x-1}}(d)}{(|R(v_k)| - x + 1)}\right] \\ &= \sum_{x=1}^a \frac{p_k^{\sigma_x}(d) - p_k^{\sigma_{x-1}}(d)}{(|R(v_k)| - x + 1)} \end{aligned}$$

It shows that the sharing $f_k^i(R)$ computed in Algorithm 6 equals the sharing defined by the Shapely value.