



#### **Reliability Concerns**



- Systems are getting bigger
  - 1024-4096 processors is today's "medium" size (>54% on the recent TOP500 List)
  - O(10,000)~ O(100,000) processor systems are being designed/deployed
- Even highly reliable HW can become an issue at scale
  - 1 node fails every 10,000 hours
  - 6,000 nodes fail every 1.6 hours
  - 64,000 nodes fail every 5 minutes



#### Needs for fault management!

Losing the entire job due to one node's failure is costly in time and CPU cycles!



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# The Big Picture

- Checkpoint/restart is widely used for fault tolerance
  - Simple
  - O intensive, may trigger a cycle of deterioration
  - Reactively handle failures through rollbacks
- Newly emerging proactive methods
  - © Good at preventing failures and avoiding rollbacks
  - 🤨 But, relies on accurate prediction of failure

#### FENCE: Fault awareness ENabled Computing Environment

- > A "fence" to protect system and appl. from severe failure impact
- Exploit the synergy between various methods to advance fault management

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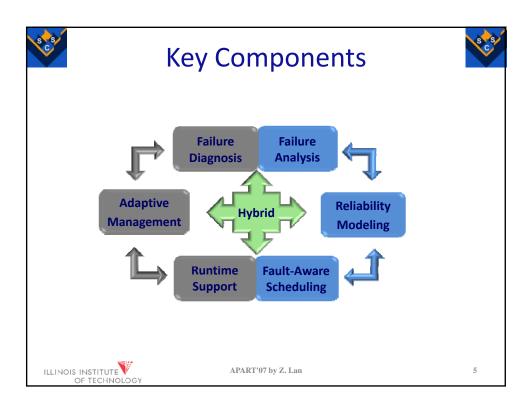


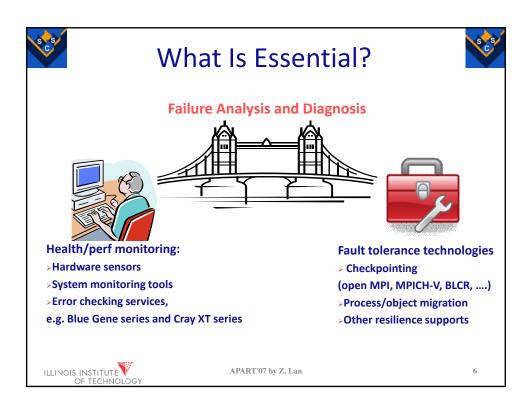
- Adopt a hybrid approach:
  - Long-term reliability modeling and scheduling enables intelligent mapping of applications to resources
  - Runtime fault resilience support allows applications to avoid imminent failures
- Explore runtime adaptation:
  - Proactive actions prevent applications from anticipated failures
  - Reactive actions minimize the impact of unforeseeable failures
- Address fundamental issues
  - Failure analysis & diagnosis
  - Adaptive management
  - Runtime support
  - Reliability modeling & scheduling





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# Failure Analysis & Diagnosis



- Goal:
  - To DISCOVER failure patterns and trends from data
  - To PROVIDE timely alerts regarding "when and where" failures are likely to occur
- Challenge:
  - Potentially overwhelming amount of information collected by error checking and monitoring tools
  - Fault patterns and root causes are often buried like needles in a haystack!
  - > How to capture a variety of fault patterns?
  - > How to achieve better diagnosis?





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7



# Failure Analysis & Diagnosis

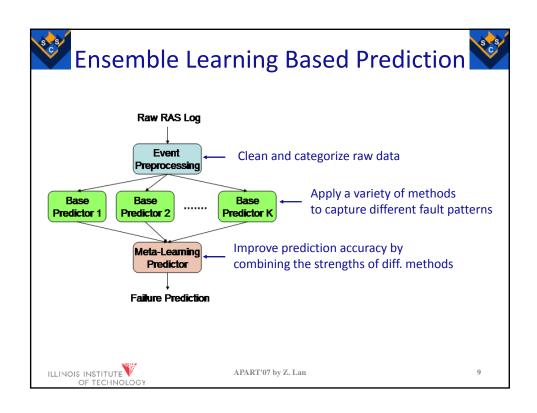


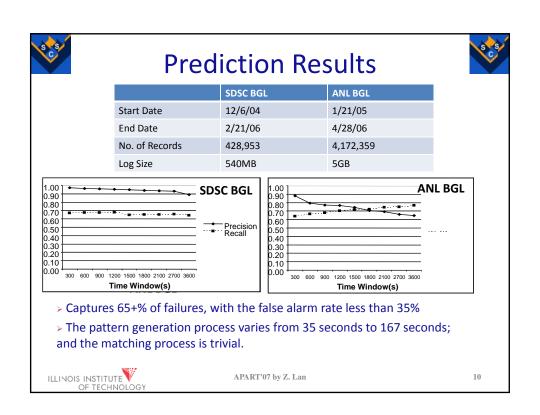
- Our approach:
  - Integrate multiple data sources: RAS log, perf data, sensor readings, ...
  - Coordinate data-driven methods: statistical learning, data mining, pattern recognition, ensemble learning (metalearning)
- The "when" question
  - Ensemble learning based prediction
- The "where" question
  - PCA (Principal component analysis) based localization

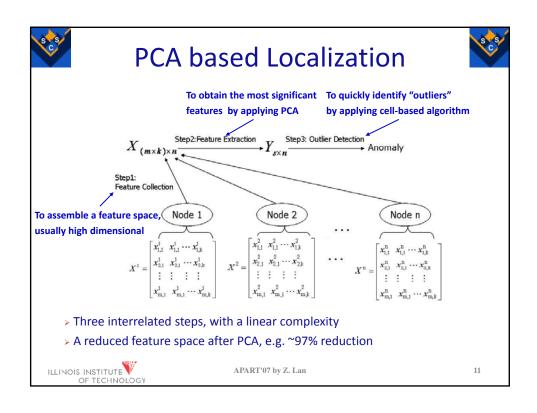


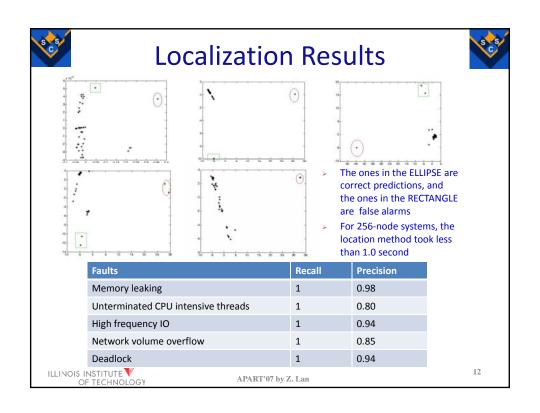
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# **Adaptive Fault Management**



- Runtime adaptation:
  - SKIP, to remove unnecessary overhead
  - CHECKPOINT, to mitigate the recovery cost in case of unpredictable failures
  - MIGRATION, to avoid anticipated failures
- Challenge:
  - Imperfect prediction
  - Overhead/benefit of different actions
  - The availability of spare resources





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13



# Adaptive Fault Management



• MIGRATION:  $E_{pm} = (2I + C_r + C_{pm}) * f_{appl} + (I + C_{pm}) * (1 - f_{appl})$ 

$$where \ f_{appl} = \begin{cases} 1 - \prod_{i=1}^{N_W^f - N_S^h} f_p & \text{if } N_W^f > N_S^h \\ 0 & \text{if } N_W^f \leq N_S^h \end{cases}$$

• CHECKPOINT:  $E_{ckp} = (2I + C_r + C_{ckp}) * f_{appl} + (I + C_{ckp}) * (1 - f_{appl})$ 

where 
$$f_{appl} = 1 - \prod_{i=1}^{N_W^f} f_p$$

• SKIP:  $E_{skip} = (C_r + (2 + l_{current} - l_{last}) * I) * f_{appl} + I * (1 - f_{appl})$ 

where 
$$f_{appl} = 1 - \prod_{i=1}^{N_W^f} f_p$$



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# **Adaptation Results**



- Fluid Stochastic Petri Net (FSPN) modeling
  - Study the impact of computation scales, number of spare nodes, prediction accuracies, and operation costs
- Case studies
  - Implemented with MPICH-VCL
  - Test applications: ENZO, Gromacs, NPB
  - Platform: TeraGrid/ANL IA32 Linux Cluster
- Results:
  - Outperforms periodic checkpointing as long as recall and precision are higher than 0.30
  - A modest allocation of spare nodes (i.e. <5%) is sufficient
  - Lower than 3% overhead



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15



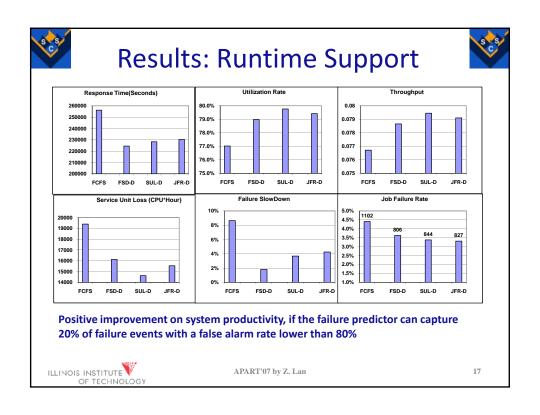
#### **Runtime Support**

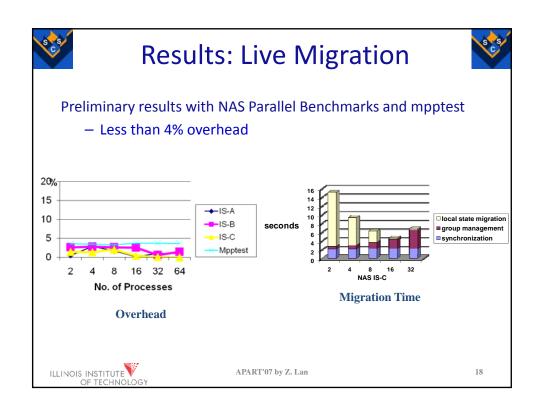


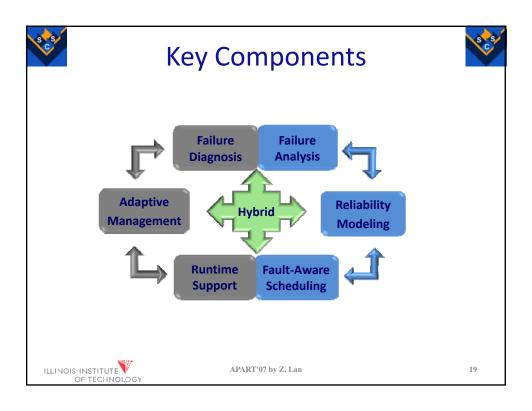
- Development /optimization of fault tolerance techniques
  - Live migration support
  - Dynamic virtual machine
  - Fast fault recovery
- System-wide node allocation strategy
  - Nodes for regular scheduling vs. spare nodes for failure prevention
- Job rescheduling strategy
  - Selection of jobs for rescheduling in case of multiple simultaneous failures



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- FENCE long-term support:
  - Investigate long-term failure modes, e.g. failure distributions
  - Analyze application performance under failures
  - Apply reliability models for fault-aware scheduling
- SC07 paper: "Performance under Failure of High-end Computing" (Thur. 2:00-2:30pm A2/A5)

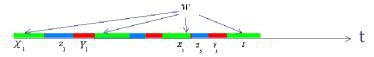


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# Performance Modeling under Failures





#### The completion time of the application:

$$T = X_1 + Y_1 + Z_1 + X_2 + Y_2 + Z_2 + \dots + X_s + Y_s + Z_s + L$$

The whole system can be considered as M/G/1 queuing system. We can derive the mean and variance of T, application execution time for single node as:

$$\begin{split} E\left(T\right) &= (\frac{1}{1 - \lambda_{f} \mu_{f}} + \lambda_{f} \mu_{c}) w \\ V\left(T\right) &= (\frac{\mu_{f}^{2} + \sigma_{f}^{2}}{\left(1 - \lambda_{f} \mu_{f}\right)^{3}} + \mu_{c}^{2} + \sigma_{c}^{2} + 2 \frac{\mu_{f} \mu_{c}}{1 - \lambda_{f} \mu_{f}}) \lambda_{f} w \end{split}$$



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#### Fault-aware Task Partition and Scheduling



Assumption: a parallel task can be partitioned into any size of subtasks. Each subtask will be assigned to a machine respectively.

Objective: scheduling a parallel task heuristically to reach a semi-optimal performance

#### Begin

List a set of idle machines in the order of their reliability over an observed time period,  $M = \{m_1, m_2, \dots m_q\};$ 

Sort the list of idle machines in an decreasing order with  $\frac{(1-\rho_{c,k})\tau_k}{1+\rho_{c,k}-\rho_{c,k}\rho_{f,k}}$ 

$$M' {=} \left\{ c_1, c_2, \dots c_q \right\};$$

$$a=1\,,\;b=\min\{|\,M'\,|,\frac{w}{4*(\mu_{f,k}+\mu_{c,k})}\}\,;$$

$$c = \lfloor (a+b)/2 \rfloor$$

/\* 
$$f(x)$$
 denotes  $E(T_{C(x)})(1 + Coe.(T_{C(x)}))$  where  $C(x) = \{c_1, c_2, \dots c_x\}$  \*/

If 
$$f(a) = \min\{f(a), f(b), f(c)\}\$$
then  $b = c$ 

Else If 
$$f(b) = \min\{f(a), f(b), f(c)\}$$
 then  $a = c$ 

Else If 
$$f(c) < f(c+1)$$
 then  $b = c$ 

Until 
$$a+1=b$$

If 
$$f(a) < f(b)$$
 then

Assign parallel task to the machine set C(a);

Else Assign parallel task to the machine set C(b);

End

Figure 7. A heuristic fault-aware task scheduling algorithm

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# **Work In Progress**



- Complete prototype systems
  - Failure analysis & diagnosis toolkit
  - Adaptive fault management library for HEC applications
  - Job scheduling/rescheduling support
- Investigate advanced predictive methods
- Provide better integration and coordination support
- Conduct extensive assessment



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23



#### **Conclusions**



- FENCE (<u>Fault awareness ENabled Computing Environment</u>) to advance fault management
  - Potential for better failure analysis and diagnosis
    - Captures 65+% of failures, with the false alarm rate less than 35%
  - Up to 50% improvement in system productivity
  - Up to 43% reduction in application completion time

"Adaptation is key" (D. Reed)

"It is not cost-effective or practical to rely on a single fault tolerance approach for all applications and systems" (Scarpazza, Villa, Petrini, Nieplochar, ...)



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