Multiflows in Multihop Wireless Networks

Peng-Jun Wan

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- Problem Description
- Practical Approximation Algorithms
- Polynomial-Time Approximation Scheme
- Summary

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A General Specification of Multihop Wireless Networks

- (V, A, \mathcal{I}) :
 - V: network nodes

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 - V: network nodes
 - A: communication links
 - (V, A): communication topology
 - \mathcal{I} : collection of independent (i.e. conflict-free) links in A
 - implicitly given by an interference model (IM)

Protocol Interference Model (IM)



Figure: (a) Communication range and interference range of each node; (b) a communication link; (c) a conflicting pair of communication links.

802.11 Interference Model (IM)



Figure: (a) Communication range and interference range of each node; (b) a communication edge; (c) a conflicting pair of communication edges.

$$S = \{(I_j, \lambda_j) \in \mathcal{I} \times \mathbb{R}_+ : 1 \le j \le k\}$$

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If the length of $S \leq 1$, it determines a link capacity function

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Capacity Region $P \subset \mathbb{R}^A_+$: convex hull of $\{\mathbf{1}^I : I \in \mathcal{I}\}$, or equivalently

 $P = \{c_S : S \text{ is a link schedule of length } \leq 1\}.$

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Maximum Multiflow (MMF): Given a set of commodities, find a link schedule S of length at most one such that the maximum multiflow subject to c_S is maximized.

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- Maximum Concurrent Multiflow (MCMF): Given a set of commodities with demands, find a link schedule S of length at most one such that the maximum concurrent multiflow subject to c_S is maximized.

• Maximum Weighted Independent Set of Links (MWISL): Given $d \in \mathbb{R}^{A}_{+}$, find an $l \in I$ such that d(I) is maximized

- Maximum Weighted Independent Set of Links (MWISL): Given $d \in \mathbb{R}^{A}_{+}$, find an $l \in I$ such that d(l) is maximized
- Shortest Weighted Link Schedule (SWLS) : Given d ∈ ℝ^A₊, find a shortest link schedule

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such that $d = \sum_{1 \leq j \leq k} \lambda_j \mathbf{1}^{l_j}$.

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Theorem If there is a capacity sub-region $Q \subseteq P$ s.t.

- Q is a μ -approximation of P, i.e., $P \subseteq \mu Q$,
- ② Q has an explicit polynomial representation, and
- ∀d ∈ Q, a fractional link schedule of length at most one for d can be computed in poly. time.

Then, both **MMF** and **MCMF** have a polynomial μ -approximation.

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Then, both **MMF** and **MCMF** have a polynomial μ -approximation.

Any $Q \subseteq P$ meeting the three above conditions is called a poly. μ -approx. capacity subregion.

 \mathcal{F}_i : set of $s_i - t_i$ flows

$$\begin{array}{l} \max \quad \text{max. multiflow} \\ \max \quad \sum_{j=1}^{k} val\left(f_{j}\right) \\ s.t. \quad f_{j} \in \mathcal{F}_{j}, \forall 1 \leq j \leq k \\ \sum_{j=1}^{k} f_{j} \in P \end{array}$$

 $\begin{array}{ll} \max & \phi \\ s.t. & f_j \in \mathcal{F}_j, \forall 1 \leq j \leq k \\ & val\left(f_j\right) \geq \phi d\left(j\right), \forall 1 \leq j \leq k \\ & \sum_{i=1}^k f_i \in P \end{array}$

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 $\begin{array}{ll} \max & Q \text{-restricted multiflow} \\ \max & \sum_{j=1}^{k} \mathit{val}\left(f_{j}\right) \\ s.t. & f_{j} \in \mathcal{F}_{j}, \forall 1 \leq j \leq k \\ & \sum_{j=1}^{k} f_{j} \in Q \end{array}$

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Step 1: solve the *Q*-restricted LP to obtain a *k*-flow $\langle f_1, f_2, \dots, f_k \rangle$, Step 2: compute a fractional link schedule of length at most one for $\sum_{j=1}^{k} f_j$.

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- Practical Approximation Algorithms
 - Episode: Independence Polytope And Fractional Coloring
 - Approximate Capacity Subregion
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• G = (V, E): an undirected graph

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- G = (V, E): an undirected graph
- \mathcal{I} : collection of independent sets of G
- Independence polytope $P \subset \mathbb{R}^{V}_+$: convex hull of $\{\mathbf{1}^{I} : I \in \mathcal{I}\}$.

• For any $d \in \mathbb{R}_+^V$, a *fractional coloring* of (G, d) is a set of k pairs $(I_j, \lambda_j) \in \mathcal{I} \times \mathbb{R}_+$ s.t.

$$\sum_{1\leq j\leq k,v\in I_j}\lambda_j=d(v),\forall v\in V.$$

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• $P = \left\{ d \in \mathbb{R}^V_+ : \chi_f(G, d) \leq 1 \right\}$

Fractional (Weighted) Coloring: Example



Figure: For the all-one demand vector *d*, $\chi_f(G, d) = 2.5$. On the other hand, $\chi(G) = 3$.

A polytope $Q \subseteq P$ is a polynomial μ -approximation of P if

- Q is a μ -approximation of P, i.e., $P \subseteq \mu Q$,
- \bigcirc Q has an explicit polynomial representation, and
First-Fit Fractional Weighted Coloring

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- Initialization: $S \leftarrow \emptyset$; $U \leftarrow \{v \in V : d(v) > 0\}$
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add (I, λ) to S
 $\forall v \in U: d(v) \leftarrow d(v) - \lambda$; if $d(v) = 0$, remove v from U

• output S

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First-Fit Fractional Weighted Coloring

• Coloring number of $S \leq n$

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- Coloring number of $S \leq n$
- Coloring weight of $S \leq \max_{1 \leq i \leq n} d(N_{\preceq}(v_i))$, where

$$N_{\preceq}(v_i) = \{v_j : 1 \le j \le i, v_j \in N(v_i)\} \\ N_{\prec}(v_i) = \{v_j : 1 \le j < i, v_j \in N(v_i)\}$$

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• $\max_{1 \le i \le n} d(N_{\le}(v_i))$: (closed) *d*-inductivity of $\langle v_1, v_2, \cdots, v_n \rangle$

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- k: # of iterations/colors
- $\forall 1 \leq j \leq k$,
 - U_j : the subset of nodes with residue demands at the beginning of the *j*-th iteration
 - (I_j, λ_j) : the pair selected in the *j*-th iteration.

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Consider an arbitrary node $v_i \in U_k$. $\forall \ 1 \leq j \leq k$, let $V_{i,j} = N_{\leq}(v_i) \cap U_j$. Then, $\forall 1 \leq j \leq k$, $I_j \cap V_{i,j} \neq \emptyset$. Hence,

$$d(N_{\preceq}(\mathbf{v}_i)) = \sum_{j=1}^k \lambda_j |I_j \cap V_{i,j}| \ge \sum_{j=1}^k \lambda_j.$$

Question: how to compute a vertex ordering with least closed *d*-inductivity?

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Question: how to compute a vertex ordering with least closed *d*-inductivity?

- $H \leftarrow G$.
- For i = n down to 1,
 - $v_i \leftarrow a$ vertex of smallest closed weighted degree in H• $H \leftarrow H - \{v_i\}$

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closed *d*-inductivity of *G*:

$$\overline{\delta}^{*}\left(\mathsf{G},\mathsf{d}\right) = \max_{U \subseteq V} \min_{u \in U} \mathsf{d}\left(\mathsf{N}_{\mathsf{G}\left[U\right]}\left[u\right]\right)$$

Theorem

The smallest-last ordering achieves the smallest d-inductivity $\overline{\delta}^*(G, d)$ among all vertex orderings.

Proof of The Theorem

For any ordering $\langle v_1, v_2, \cdots, v_n \rangle$,

$$\max_{1\leq i\leq n}d\left(N_{\preceq}\left(v_{i}\right)\right)\geq\overline{\delta}^{*}\left(G,d\right).$$

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For any ordering $\langle v_1, v_2, \cdots, v_n \rangle$,

$$\max_{1\leq i\leq n}d\left(N_{\preceq}\left(\mathsf{v}_{i}\right)\right)\geq\overline{\delta}^{*}\left(\mathsf{G},\mathsf{d}\right).$$

Let $U \subseteq V$ be s.t.

$$\overline{\delta}^{*}(G, d) = \min_{u \in U} d\left(N_{G[U]}[u]\right)$$

and j be the last index such that $v_j \in U$. Then,

$$\max_{1 \leq i \leq n} d\left(N_{\preceq}\left(v_{i}\right)\right) \geq d\left(N_{\preceq}\left(v_{j}\right)\right) \geq d\left(N_{G[U]}\left[v_{j}\right]\right) = \overline{\delta}^{*}\left(G, d\right).$$

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For the smallest-last ordering $\langle v_1, v_2, \cdots, v_n \rangle$,

$$\max_{1\leq i\leq n}d\left(N_{\preceq}\left(v_{i}\right)\right)\leq\overline{\delta}^{*}\left(G,d\right).$$

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For the smallest-last ordering $\langle v_1, v_2, \cdots, v_n \rangle$,

$$\max_{1\leq i\leq n}d\left(N_{\preceq}\left(v_{i}\right)\right)\leq\overline{\delta}^{*}\left(G,d\right).$$

For any $1 \leq i \leq n$, let $V_i = \{v_1, v_2, \cdots, v_i\}$. Then,

$$d\left(\mathsf{N}_{\preceq}(\mathsf{v}_{i})\right) = \min_{u \in V_{i}} d\left(\mathsf{N}_{G[V_{i}]}[u]\right) \leq \overline{\delta}^{*}\left(\mathsf{G},\mathsf{d}\right).$$

Hence,

$$\max_{1\leq i\leq n}d\left(N_{\preceq}\left(v_{i}\right)\right)\leq\overline{\delta}^{*}\left(G,d\right).$$

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$$\langle v_1, v_2, \cdots, v_n \rangle$$
: a vertex ordering

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$$\langle v_1, v_2, \cdots, v_n \rangle$$
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• Its Inductive LIN:

$$\alpha^* = \max_{1 \leq i \leq n} \left\{ |I| : I \in \mathcal{I}, I \subseteq N_{\prec}(v_i) \right\}.$$

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• Its Inductive LIN:

$$\alpha^* = \max_{1 \leq i \leq n} \left\{ |I| : I \in \mathcal{I}, I \subseteq N_{\prec}(v_i) \right\}.$$

• $\forall d \in \mathbb{R}^V_+$,

$$\overline{\delta}^{*}(G,d) \leq \max_{1 \leq i \leq n} d(N_{\preceq}(v_i)) \leq \alpha^{*} \chi_{f}(G,d).$$

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 $\forall 1 \leq i \leq n$,

$$\chi_{f}(G, d) \geq d(N_{\prec}(v_{i})) / \alpha^{*} + d(v_{i})$$

$$\Rightarrow d(N_{\preceq}(v_{i})) \leq \alpha^{*}(\chi_{f}(G, d) - d(v_{i})) + d(v_{i})$$

$$= \alpha^{*}\chi_{f}(G, d) - (\alpha^{*} - 1) d(v_{i})$$

$$\leq \alpha^{*}\chi_{f}(G, d) - (\alpha^{*} - 1) \min_{v \in V} d(v).$$

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The polytope

$$Q = \left\{ d \in \mathbb{R}^V_+ : \max_{1 \le i \le n} d\left(N_{\preceq}\left(v_i\right)\right) \le 1 \right\}.$$

is a polynomial α^* -approx. of *P*.

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• D = (V, A): an orientation of G

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- D = (V, A): an orientation of G
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$$eta^* = \max_{u \in V} \left\{ |I| : I \in \mathcal{I}, I \subseteq \mathcal{N}_D^{in}(v)
ight\}.$$

• $\forall d \in \mathbb{R}^V_+$,

 $\overline{\delta}^{*}\left(G,d\right) \leq \max_{v \in V} \left(d\left(v\right) + 2d\left(N_{D}^{in}\left(v\right)\right)\right) \leq 2\beta^{*}\chi_{f}\left(G,d\right).$

For any $U \subseteq V$, $\exists u \in U$ s.t.

$$d\left(N_{D[U]}^{in}\left(u\right)\right) \geq d\left(N_{D[U]}^{out}\left(u\right)\right).$$

Thus,

$$d\left(N_{G[U]}\left[u\right]\right) = d\left(u\right) + d\left(N_{D[U]}^{in}\left(u\right)\right) + d\left(N_{D[U]}^{out}\left(u\right)\right)$$
$$\leq d\left(u\right) + 2d\left(N_{D[U]}^{in}\left(u\right)\right)$$
$$\leq d\left(u\right) + 2d\left(N_{D}^{in}\left(u\right)\right)$$
$$\leq \max_{v \in V} \left(d\left(v\right) + 2d\left(N_{D}^{in}\left(v\right)\right)\right).$$

So,

$$\overline{\delta}^{*}(G,d) \leq \max_{v \in V} \left(d(v) + 2d(N_{D}^{in}(v)) \right).$$

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 $\forall v \in V$,

$$\begin{split} \chi_{f}\left(G,d\right) &\geq d\left(N_{D}^{in}\left(v\right)\right)/\beta^{*} + d\left(v\right) \\ \Rightarrow d\left(N_{D}^{in}\left(v\right)\right) &\leq \beta^{*}\left(\chi_{f}\left(G,d\right) - d\left(v\right)\right) \\ \Rightarrow d\left(v\right) + 2d\left(N_{D}^{in}\left(v\right)\right) &\leq 2\beta^{*}\chi_{f}\left(G,d\right) - (2\beta^{*} - 1)d\left(v\right) \end{split}$$

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The polytope

$$Q = \left\{ d \in \mathbb{R}^V_+ : \max_{v \in V} \left(d\left(v\right) + 2d\left(N^{in}_D\left(v\right)\right)
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is a polynomial $2\beta^*$ -approx. of *P*

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- Problem Description
- Practical Approximation Algorithms
 - Episode: Independence Polytope And Fractional Coloring
 - Approximate Capacity Subregion
- Polynomial-Time Approximation Scheme
- Summary

• Orientation of the conflict graph: for any a pair of conflicting links $a_1 = (u_1, v_1)$ and $a_2 = (u_2, v_2)$

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• if v_1 is in the interference range of u_2 , take (a_2, a_1) ;

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 - if v₁ is in the interference range of u₂, take (a₂, a₁);
 - otherwise, take (a_1, a_2) .

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- Q: inward independence polytope of this orientation
- Orientation of the conflict graph: for any a pair of conflicting links $a_1 = (u_1, v_1)$ and $a_2 = (u_2, v_2)$
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- Orientation of the conflict graph: for any a pair of conflicting links $a_1 = (u_1, v_1)$ and $a_2 = (u_2, v_2)$
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 - otherwise, take (a_1, a_2) .
- Q: inward independence polytope of this orientation
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Lemma

$$\beta^* \leq \lceil \pi / \arcsin \frac{c-1}{2c} \rceil - 1$$
, and hence Q is a poly.
2 $\left(\lceil \pi / \arcsin \frac{c-1}{2c} \rceil - 1 \right)$ -approx capacity subregion.

• Lexicographic ordering: sort all edges in the lexicographic order of their right endpoints

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Lemma

 $\alpha^* \leq 7$ and hence Q is a poly. 7-approx capacity subregion.

• Interference radius decreasing ordering: sort all edges in the decreasing order of their larger interference radii

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Lemma

 $\alpha^* \leq 23$ hence Q is a poly. 23-approx capacity subregion.

- Problem Description
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Summary

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Theorem Restricted to a network class \mathcal{N} , if there is a poly. (resp., a poly. μ -approx.) alg. for **MWISL**, then there is a poly. (resp., a poly. μ -approx.) alg. for (1) **SWLS**, (2) **MMF**, and (3) **MCMF**.

Ellipsoid Method with (Approx.) Separation Oracle

$$\begin{array}{l} \mathcal{P}_{j} \text{ for } 1 \leq j \leq k \text{: the set of paths for commodity } j \\ \mathcal{P} \text{: union of } \mathcal{P}_{1}, \cdots, \mathcal{P}_{k} \\ \mathcal{P}_{e} \text{ for } e \in A \text{: the set of paths in } \mathcal{P} \text{ that use link } e \\ \mathcal{I}_{e} \text{ for } e \in A \text{: the set of } I \text{ in } \mathcal{P} \text{ containing } e \end{array}$$

Primary (path-flow) LP for MMF		dual LP	
max	$x(\mathcal{P})$	min	τ
s.t.	$x\left(\mathcal{P}_{e} ight)\leq\lambda\left(\mathcal{I}_{e} ight)$, $orall e\in\mathcal{A}$	s.t.	$y(p) \geq 1, orall p \in \mathcal{P}$
	$\lambda\left(\mathcal{I} ight)\leq1$		$y(I) \leq \tau, \forall I \in \mathcal{I}$
	$x \in \mathbb{R}^{\mathcal{P}}_+$, $\lambda \in \mathbb{R}^{\mathcal{I}}_+$		$y\in \mathbb{R}^{\mathcal{A}}_+$, $ au\in \mathbb{R}_+$

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Approaches:

- for the first two classes: shifting strategy + dynamic programming
- for the third class: polynomial growth

Theorem Restricted to any of the following three network classes, all of **MWISL**, **SWLS**, **MMF**, and **MCMF** have a PTAS:

- 802.11 IM;
- Protocol IM, and the interference radius of each node is at least c times its communication radius for some constant c > 1;
- Protocol IM, and every k-hop neighborhood in the conflict-graph contains at most O (k^c) independent links for some constant c > 0.

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MWISL

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- PTAS in broader ranges of networks