Multiflows under Protocol Interference Model

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- Introduction
- Adaptive Zero-Sum Game
- Weak Dualities
- Flow Augmentation Methods
- Extensions to Budgeted Variants

• Multihop wireless network: (V, A, I)

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- k unicast requests.

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- k unicast requests.
- \mathcal{F}_i : the set of flows of the *j*-th request
- \mathcal{P}_j : the set of paths of the *j*-th request
- A k-flow is a sequence $f = \langle f_1, f_2, \cdots, f_k \rangle$ with $f_j \in \mathcal{F}_j \ \forall j \in [k]$

Theorem

If there is a polynomial (respectively, a polynomial μ -approximation) algorithm for **MWISL**, then there exist polynomial time μ -approximate algorithms for all four variants of multiflow problems.

Theorem

All four variants of multiflow problems under protocol interference model have a PTAS.

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Approximation-Preserving Reduction to Polynomial Approximate Capacity Subregions

Theorem

If there exists a polynomial μ -approximate capacity subregion, then there exist polynomial time μ -approximate algorithms for each of the four variants of multiflow problems.

 $\Omega:$ capacity region

$\begin{array}{ll} & \textbf{MWMF} \\ \max & \sum_{j=1}^{k} w_{j} val\left(f_{j}\right) \\ s.t. & f_{j} \in \mathcal{F}_{j}, \forall 1 \leq j \leq k \\ & \sum_{j=1}^{k} f_{j} \in \Omega \end{array}$

MCMF

$$\begin{array}{ll} \max & \phi \\ s.t. & f_j \in \mathcal{F}_j, \forall 1 \leq j \leq k \\ & val\left(f_j\right) \geq \phi w_j, \forall 1 \leq j \leq k \\ & \sum_{j=1}^k f_j \in \Omega \end{array}$$

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 Φ : a poly. μ -approx. capacity subregion

 $\begin{array}{ll} \Phi \text{-restricted } \textbf{MWMF} \\ \max & \sum_{j=1}^{k} w_j \text{val}\left(f_j\right) \\ s.t. & f_j \in \mathcal{F}_j, \forall 1 \leq j \leq k \\ & \sum_{j=1}^{k} f_j \in \Phi \end{array}$

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Step 1: solve the Φ -restricted LP to obtain a k-flow $f = \langle f_1, f_2, \dots, f_k \rangle$, Step 2: compute a fractional link schedule S of $\sum_{j=1}^k f_j$ Step 3: scale f and S by a factor 1/||S||approximation bound: μ Restrictions to the polynomial capacity subregions constructed in the previous chapter yield the following approximation bounds:

•
$$2\left(\left\lceil \pi / \arcsin \frac{c-1}{2c} \right\rceil - 1\right)$$
 in general,

• $\left\lceil \frac{r+1}{h(r)} \right\rceil + 1$ with uniform interference radii.

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• Parameters:

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• D: an orientation of D with ILIN μ

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- $\varepsilon \in (0,1]$: the trade-off parameter

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• Flow Augmentation Stage: Compute a k-flow f s.t.

$$\frac{\sum_{j \in [k]} w_j \operatorname{val}(f_j)}{\Delta_D^{\operatorname{in}}\left(\sum_{j \in [k]} f_j\right)} \geq \frac{\operatorname{opt}}{(1+\varepsilon)\,\mu}.$$

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- Link-Scheduling Stage: Compute a link schedule S of x with GLS.
- Scaling Stage: Scale both Π and ${\cal S}$ by a factor $1/\,\|{\cal S}\|$ and then return them.

Approximation Bound

• $2(1+\varepsilon)\mu$ in general:

$$\frac{\sum_{j \in [k]} w_j \operatorname{val}(f_j)}{\|\mathcal{S}\|} \geq \frac{\sum_{j \in [k]} w_j \operatorname{val}(f_j)}{\Delta^* \left(\sum_{j \in [k]} f_j\right)}$$
$$\geq \frac{\sum_{j \in [k]} w_j \operatorname{val}(f_j)}{2\Delta_D^{in} \left(\sum_{j \in [k]} f_j\right)} \geq \frac{opt}{2(1+\varepsilon)\mu}.$$

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• $(1 + \varepsilon) \mu$ if *D* is acyclic:

$$\frac{\sum_{j \in [k]} w_j \operatorname{val}(f_j)}{\|\mathcal{S}\|} \geq \frac{opt}{(1+\varepsilon)\,\mu}.$$

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$$\frac{\min_{j \in [k]} \frac{\operatorname{val}(f_j)}{w_j}}{\Delta_D^{in}\left(\sum_{j \in [k]} f_j\right)} \ge \frac{opt}{(1+\varepsilon)\,\mu}$$

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- How to define an appropriate interference costs of links and paths?
- How much flow should be routed along those cheapest paths?

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 - The adversaries picks their losses subjected to the **Normalization Rule**: the maximum value of the individual losses = 1.

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 - The agent collects the profit according to the **Zero-Sum Rule**: the profit = expected loss of the adversaries w.r.t the agent's binding strategy.

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 - The agent collects the profit according to the **Zero-Sum Rule**: the profit = expected loss of the adversaries w.r.t the agent's binding strategy.
- Objective: to realize asap maximum cumulative loss of adversaries $\leq (1+\varepsilon) \times$ cumulative profit of the agent.

L(e): the cumulative loss of e ∈ E at the beginning of a round
The probability of e ∈ E: ∝ (1 + ε)^{L(e)}.

Repeat

$$t = \left\lceil rac{m \ln m}{\ln (1 + arepsilon) - rac{arepsilon}{1 + arepsilon}}
ight
ceil$$

rounds:

Declaration of exponential binding strategies by agent

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Repeat

$$t = \left\lceil rac{m \ln m}{\ln (1 + arepsilon) - rac{arepsilon}{1 + arepsilon}}
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rounds:

- **Declaration of exponential binding strategies** by agent
- **@** Generation of loss by adversary s.t. the Normalization Rule

Analysis of The Game

 $t=O\left(arepsilon^{-2}m\ln m
ight)$ as

$$\begin{split} &\ln\left(1+\varepsilon\right) - \frac{\varepsilon}{1+\varepsilon} = -\ln\left(1-\frac{\varepsilon}{1+\varepsilon}\right) - \frac{\varepsilon}{1+\varepsilon} \\ &\geq \frac{1}{2}\left(\frac{\varepsilon}{1+\varepsilon}\right)^2 = \frac{1}{2}\left(1+1/\varepsilon\right)^{-2}. \end{split}$$

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Theorem

At the end of the game, the maximum cumulative loss of the adversaries is at most $1 + \varepsilon$ times the cumulative profit of the agent.

• For each round $r \in [t]$

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- For each round $r \in [t]$
 - $L_r(e)$: cumulative loss of $e \in E$ at the end of round r

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- $L_0(e) = 0, \forall e \in E; \ell_0 = 0.$

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$$L_0(e) = 0, \forall e \in E; \ \ell_0 = 0.$$

• $y_r(e) = (1 + \varepsilon)^{L_r(e)}$: $\forall 0 \le r \le t$ and $\forall e \in E$

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- $y_r(e) = (1 + \varepsilon)^{L_r(e)}$: $\forall 0 \le r \le t$ and $\forall e \in E$
- Zero-Sum Rule

$$\ell_{r} - \ell_{r-1} = \sum_{e \in E} \frac{y_{r-1}(e)}{y_{r-1}(E)} \left(L_{r}(e) - L_{r-1}(e) \right).$$

Analysis of The Game

$$y_{r}(E) = \sum_{e \in E} y_{r}(e) = \sum_{e \in E} y_{r-1}(e) (1+\varepsilon)^{L_{r}(e)-L_{r-1}(e)}$$

$$\leq \sum_{e \in E} y_{r-1}(e) (1+\varepsilon (L_{r}(e)-L_{r-1}(e)))$$

$$= \sum_{e \in E} y_{r-1}(e) + \varepsilon \sum_{e \in E} y_{r-1}(e) (L_{r}(e)-L_{r-1}(e))$$

$$= y_{r-1}(E) \left(1+\varepsilon \sum_{e \in E} \frac{y_{r-1}(e)}{y_{r-1}(E)} (L_{r}(e)-L_{r-1}(e))\right)$$

$$= y_{r-1}(E) (1+\varepsilon (\ell_{r}-\ell_{r-1}))$$

$$\leq y_{r-1}(E) \exp (\varepsilon (\ell_{r}-\ell_{r-1})).$$

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$y_t(E) \leq y_0(E) \prod_{r=1}^t \exp\left(\varepsilon \left(\ell_r - \ell_{r-1}\right)\right) = m \exp\left(\varepsilon \ell_t\right).$

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$$y_t(E) \leq y_0(E) \prod_{r=1}^t \exp\left(\varepsilon \left(\ell_r - \ell_{r-1}\right)\right) = m \exp\left(\varepsilon \ell_t\right).$$

$$\epsilon \ell_{t} \geq \ln rac{y_{t}(E)}{m} \geq \ln rac{y_{t}(e)}{m} = L_{t}(e) \ln (1+\epsilon) - \ln m, \forall e \in E$$

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$$L_t(e) \ge rac{t}{m} \ge rac{\ln m}{\ln (1+\varepsilon) - rac{\varepsilon}{1+\varepsilon}}$$

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 $L_t(e) \ln (1+\varepsilon) - \ln m \ge rac{\varepsilon}{1+\varepsilon} L_t(e).$

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$$L_{t}(e) \geq \frac{t}{m} \geq \frac{\ln m}{\ln (1+\varepsilon) - \frac{\varepsilon}{1+\varepsilon}}.$$
$$L_{t}(e) \ln (1+\varepsilon) - \ln m \geq \frac{\varepsilon}{1+\varepsilon} L_{t}(e) .$$
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$$\varepsilon \ell_{t} \geq L_{t}(e) \ln (1+\varepsilon) - \ln m \geq \frac{\varepsilon}{1+\varepsilon} L_{t}(e)$$
$$L_{t}(e) \leq (1+\varepsilon) \ell_{t}.$$

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• y: positive function on A

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- *y*: positive function on *A*
- \hat{y} : length function on A induced by y

 $\widehat{y}(a) = y\left(N_D^{out}\left[a\right]\right)$

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- *y*: positive function on *A*
- \hat{y} : length function on A induced by y

$$\widehat{y}\left(\mathbf{a}
ight)=y\left(N_{D}^{out}\left[\mathbf{a}
ight]
ight)$$

• $dist_j(\hat{y}) \ \forall j \in [k]$: length of a shortest *j*-path w.r.t. \hat{y}

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• The weight of the maximum weighted multiflow

$$\leq \mu y\left(A
ight) \max_{j\in [k]}rac{w_{j}}{dist_{j}\left(\widehat{y}
ight) }.$$

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The weight of the maximum weighted multiflow

$$\leq \mu y\left(A
ight) \max_{j\in\left[k
ight]}rac{w_{j}}{dist_{j}\left(\widehat{y}
ight)}.$$

• The concurrency of the maximum concurrent multiflow is at most

$$\leq \mu rac{y(A)}{\sum_{j \in [k]} w_j dist_j(\widehat{y})}.$$

A non-negative function x on $\bigcup_{j \in [k]} \mathcal{P}_j$ is said to be a *path-flow* decomposition of a multiflow $f = (f_1, \cdots, f_k)$ if

$$f_{j}\left(a
ight)=\sum_{oldsymbol{P}\in\mathcal{P}_{j}}\left|\left\{a
ight\}\cap oldsymbol{P}
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Lemma

For any path-flow decomposition x of a multiflow $f = (f_1, \cdots, f_k)$,

$$\sum_{i \in [k]} \sum_{P \in \mathcal{P}_{j}} x\left(P\right) \widehat{y}\left(P\right) = \sum_{a \in A} y\left(a\right) \sum_{j \in [k]} f_{j}\left(N_{D}^{in}\left[a\right]\right)$$

$$\begin{split} &\sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \widehat{y}\left(P\right) \\ &= \sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \sum_{b \in P} \widehat{y}\left(b\right) \\ &= \sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \sum_{b \in P} y\left(N_D^{out}\left[b\right]\right) \\ &= \sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \sum_{b \in A} \left|\{b\} \cap P\right| y\left(N_D^{out}\left[b\right]\right) \\ &= \sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \sum_{b \in A} \left|\{b\} \cap P\right| \sum_{a \in N_D^{out}\left[b\right]} y\left(a\right) \\ &= \sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \sum_{b \in A} \left|\{b\} \cap P\right| \sum_{a \in A} y\left(a\right) \left|\{b\} \cap N_D^{in}\left[a\right]\right| \end{split}$$

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$$\begin{split} &\sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \sum_{b \in A} \left|\{b\} \cap P\right| \sum_{a \in A} y\left(a\right) \left|\{b\} \cap N_D^{in}\left[a\right]\right| \\ &= \sum_{a \in A} y\left(a\right) \sum_{j \in [k]} \sum_{b \in A} \left|\{b\} \cap N_D^{in}\left[a\right]\right| \sum_{P \in \mathcal{P}_j} \left|\{b\} \cap P\right| x\left(P\right) \\ &= \sum_{a \in A} y\left(a\right) \sum_{j \in [k]} \sum_{b \in A} \left|\{b\} \cap N_D^{in}\left[a\right]\right| f_j\left(b\right) \\ &= \sum_{a \in A} y\left(a\right) \sum_{j \in [k]} \sum_{b \in N_D^{in}\left[a\right]} f_j\left(b\right) \\ &= \sum_{a \in A} y\left(a\right) \sum_{j \in [k]} f_j\left(N_D^{in}\left[a\right]\right), \end{split}$$

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Feasible Multiflow

Lemma

For any feasible multiflow $f = (f_1, \dots, f_k)$,

$$\sum_{i \in [k]} dist_{j}\left(\widehat{y}
ight)$$
 val $(f_{j}) \leq \mu y\left(A
ight)$

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Feasible Multiflow

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$$\begin{split} &\sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \widehat{y}\left(P\right) \geq \sum_{j \in [k]} \sum_{P \in \mathcal{P}_j} x\left(P\right) \textit{dist}_j\left(\widehat{y}\right) \\ &= \sum_{j \in [k]} \textit{dist}_j\left(\widehat{y}\right) \sum_{P \in \mathcal{P}_j} x\left(P\right) = \sum_{j \in [k]} \textit{dist}_j\left(\widehat{y}\right) \textit{val}\left(f_j\right). \end{split}$$

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Feasible Multiflow

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 $f = (f_1, \cdots, f_k)$: a maximum weighted multiflow

$$\mu y (A) \ge \sum_{j \in [k]} dist_j (\widehat{y}) \text{ val } (f_j) = \sum_{j \in [k]} \frac{dist_j (\widehat{y})}{w_j} w_j \text{ val } (f_j)$$
$$\ge \left(\min_{j \in [k]} \frac{dist_j (\widehat{y})}{w_j} \right) \sum_{j \in [k]} w_j \text{ val } (f_j)$$

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$$\ge \left(\min_{j \in [k]} \frac{dist_j(\widehat{y})}{w_j}\right) \sum_{j \in [k]} w_j \operatorname{val}(f_j)$$

$$\sum_{j \in [k]} w_j \operatorname{val}(f_j) \le \mu \frac{y(A)}{\min_{j \in [k]} \frac{\operatorname{dist}_j(\widehat{y})}{w_j}}$$

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$f = (f_1, \cdots, f_k)$: a maximum concurrent multiflow

$$\mu y(A) \ge \sum_{j \in [k]} dist_j(\widehat{y}) val(f_j) = \sum_{j \in [k]} w_j dist_j(\widehat{y}) \frac{val(f_j)}{w_j}$$
$$\ge \left(\min_{j \in [k]} \frac{val(f_j)}{w_j}\right) \sum_{j \in [k]} w_j dist_j(\widehat{y})$$

$$\min_{j \in [k]} \frac{\textit{dist}_{j}\left(\widehat{y}\right)}{w_{j}} \leq \mu \frac{y\left(A\right)}{\sum_{j \in [k]} w_{j}\textit{dist}_{j}\left(\widehat{y}\right)}$$

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Interference-Aware Congestion, Costs, and Lengths

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$$f = (f_1, \cdots, f_k)$$
: a multiflow

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- $f = (f_1, \cdots, f_k)$: a multiflow
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- congestion cost of a link a due to $f: y_f(a) = (1 + \varepsilon)^{\sum_{j \in [k]} f_j(N_D^{in}[a])}$

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- congestion cost of a link a due to f: $y_f(a) = (1 + \epsilon)^{\sum_{j \in [k]} f_j(N_D^{in}[a])}$
- *length* of a link *a* due to $f: \hat{y}_f(a) = y_f(N_D^{out}[a])$.

$$\begin{aligned} \forall j \in [k], f_j \leftarrow \mathbf{0}; \\ \text{repeat} \left\lceil \frac{m \ln m}{\ln(1+\varepsilon) - \frac{\varepsilon}{1+\varepsilon}} \right\rceil \text{ times} \\ \forall j \in [k], P_j \leftarrow \text{ a shortest } j\text{-path w.r.t. } \widehat{y}_f; \\ j \leftarrow \arg \max_{j \in [k]} \frac{w_j}{\widehat{y}_f(P_j)}; \\ \delta \leftarrow \frac{1}{\max_{a \in A} |P_j \cap N_D^{in}[a]|}; \\ \forall a \in P_j, f_j(a) \leftarrow f_j(a) + \delta; \end{aligned}$$

Interpretation As An Adaptive Zero-Sum Game

• Each link $a \in A$ corresponds to an adversary

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- The cumulative loss of *a* = its interference-aware *congestion* due to the current *f*

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- The cumulative loss of *a* = its interference-aware *congestion* due to the current *f*
- σ is determined by the Normalization Rule: the loss of each link a is

 $\delta\left|P_{j}\cap N_{D}^{in}\left[a\right]\right|.$

• By Zero-Sum Rule, the agent earns a profit in a round

$$\frac{1}{y_{f}(A)}\sum_{a\in A}y_{f}(a)\,\delta\left|P_{j}\cap N_{D}^{in}\left[a\right]\right| = \frac{\delta}{y_{f}(A)}\widehat{y}_{f}(P_{j})$$
$$= \frac{\delta w_{j}}{y_{f}(A)}\frac{dist_{j}\left(\widehat{y}_{f}\right)}{w_{j}} \leq \mu\frac{\delta w_{j}}{opt}.$$

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$$\frac{1}{y_{f}(A)}\sum_{a\in A}y_{f}(a)\,\delta\left|P_{j}\cap N_{D}^{in}\left[a\right]\right| = \frac{\delta}{y_{f}(A)}\widehat{y}_{f}(P_{j})$$
$$= \frac{\delta w_{j}}{y_{f}(A)}\frac{dist_{j}\left(\widehat{y}_{f}\right)}{w_{j}} \leq \mu\frac{\delta w_{j}}{opt}.$$

 At the end of the last round, the cumulative profit of the agent is at most

$$u \frac{\sum_{j \in [k]} w_j val(f_j)}{opt}.$$

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Profit vs. Maximum Loss

$$\Delta_{D}^{in}\left(\sum_{j\in[k]}f_{j}\right)\leq\left(1+\varepsilon\right)\mu\frac{\sum_{j\in[k]}w_{j}val\left(f_{j}\right)}{opt}$$

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Profit vs. Maximum Loss

$$\Delta_D^{in}\left(\sum_{j\in[k]}f_j\right) \le (1+\varepsilon)\,\mu\frac{\sum_{j\in[k]}w_j\,\mathsf{val}\,(f_j)}{opt}$$

$$\frac{\sum_{j \in [k]} w_j \operatorname{val}(f_j)}{\Delta_D^{\operatorname{in}}\left(\sum_{j \in [k]} f_j\right)} \geq \frac{\operatorname{opt}}{\left(1 + \varepsilon\right) \mu}.$$

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$$\begin{aligned} \forall j \in [k], f_j \leftarrow \mathbf{0}; \\ \text{repeat} \left\lceil \frac{m \ln m}{\ln(1+\varepsilon) - \frac{\varepsilon}{1+\varepsilon}} \right\rceil \text{ times} \\ \forall j \in [k], P_j \leftarrow \text{ a shortest } j\text{-path w.r.t. } \widehat{y}_f; \\ \sigma \leftarrow \frac{1}{\max_{a \in A} \sum_{j \in [k]} w_j |N_D^{in}[a] \cap P_j|}; \\ \forall j \in [k] \text{ and } a \in P_j, f_j(a) \leftarrow f_j(a) + \sigma w_j; \end{aligned}$$

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$$\sigma \sum_{j \in [k]} w_j \left| P_j \cap N_D^{in}\left[a \right] \right|.$$

• By Zero-Sum Rule, the agent earns a profit in a round

$$\begin{split} &\frac{1}{y_{f}\left(A\right)}\sum_{a\in A}y_{f}\left(a\right)\sigma\sum_{j\in[k]}w_{j}\left|P_{j}\cap N_{D}^{in}\left[a\right]\right| \\ &=\frac{\sigma}{y_{f}\left(A\right)}\sum_{j\in[k]}w_{j}\widehat{y}_{f}\left(P_{j}\right)=\frac{\sigma}{y_{f}\left(A\right)}\sum_{j\in[k]}w_{j}dist_{j}\left(\widehat{y}_{f}\right)\leq\mu\frac{\sigma}{opt}. \end{split}$$

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• By Zero-Sum Rule, the agent earns a profit in a round

$$\frac{1}{y_f(A)} \sum_{a \in A} y_f(a) \sigma \sum_{j \in [k]} w_j \left| P_j \cap N_D^{in}[a] \right|$$

= $\frac{\sigma}{y_f(A)} \sum_{j \in [k]} w_j \widehat{y}_f(P_j) = \frac{\sigma}{y_f(A)} \sum_{j \in [k]} w_j dist_j(\widehat{y}_f) \le \mu \frac{\sigma}{opt}.$

 At the end of the last round, the cumulative profit of the agent is at most

$$u \frac{\min_{j \in [k]} val(f_j) / w_j}{opt},$$

Profit vs. Maximum Loss

$$\Delta_D^{in}\left(\sum_{j\in[k]}f_j\right) \le (1+\varepsilon)\,\mu\frac{\min_{j\in[k]}\mathsf{val}\,(f_j)\,/\,w_j}{\mathsf{opt}}$$

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Profit vs. Maximum Loss

$$\Delta_D^{in}\left(\sum_{j\in[k]}f_j\right) \le (1+\varepsilon)\,\mu\frac{\min_{j\in[k]}\mathsf{val}\,(f_j)\,/\,w_j}{\mathsf{opt}}$$

$$\frac{\min_{j \in [k]} val\left(f_{j}\right) / w_{j}}{\Delta_{D}^{in}\left(\sum_{j \in [k]} f_{j}\right)} \geq \frac{opt}{\left(1 + \varepsilon\right) \mu}$$

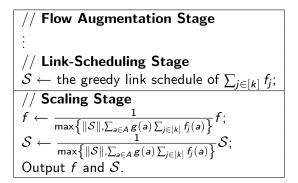
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Flow Augmentation Method for Budgeted Multiflows



A Virtual Link Representing Budget Constraint

• g: flow expense function of A

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- "virtual" link a^+ : disjoint from all links in A

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- "virtual" link a^+ : disjoint from all links in A
- $A^+ = A \cup \{a^+\}$

• y: positive function on A^+

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- y: positive function on A^+
- \hat{y} : length function on A induced by y:

$$\widehat{y}\left(\mathbf{a}
ight)=y\left(N_{D}^{out}\left[\mathbf{a}
ight]
ight)+y\left(\mathbf{a}^{+}
ight)g\left(\mathbf{a}
ight)$$

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- y: positive function on A^+
- \hat{y} : length function on A induced by y:

$$\widehat{y}\left(\mathbf{a}
ight)=y\left(N_{D}^{out}\left[\mathbf{a}
ight]
ight)+y\left(\mathbf{a}^{+}
ight)g\left(\mathbf{a}
ight)$$

• $dist_j(\widehat{y}) \ \forall j \in [k]$: length of a shortest j-path w.r.t. \widehat{y}

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• The weight of the budgeted maximum weighted multiflow

$$\leq \mu \frac{y\left(A^{+}\right)}{\min_{j \in [k]} dist_{j}\left(\widehat{y}\right) / w_{j}}.$$

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• The weight of the budgeted maximum weighted multiflow

$$\leq \mu \frac{y\left(A^{+}\right)}{\min_{j\in[k]} dist_{j}\left(\widehat{y}\right) / w_{j}}.$$

The concurrency of the budgeted maximum concurrent multiflow is at most

$$\leq \mu \frac{y(A^{+})}{\sum_{j \in [k]} w_j dist_j(\widehat{y})}.$$

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Path-Flow Decomposition

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Lemma

For any path-flow decomposition x of a multiflow $f = (f_1, \dots, f_k)$,

$$\sum_{j \in [k]} \sum_{P \in \mathcal{P}_{j}} x(P) \, \widehat{y}(P) = \sum_{a \in A} y(a) \sum_{j \in [k]} f_{j}\left(N_{D}^{in}\left[a\right]\right) \\ + y(a^{+}) \sum_{a \in A} g(a) \sum_{j \in [k]} f_{j}(a)$$

Lemma

For any feasible multiflow $f = (f_1, \cdots, f_k)$,

$$\sum_{j\in \left[k
ight]}{ extsf{dist}_{j}\left(\widehat{y}
ight) extsf{val}\left(f_{j}
ight)}\leq\mu y\left(A^{+}
ight)$$

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• $f = (f_1, \cdots, f_k)$: a multiflow

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- $f = (f_1, \cdots, f_k)$: a multiflow
- congestion of $a \in A$ due to f:

 $\sum_{j\in\left[k\right]}f_{j}\left(N_{D}^{in}\left[a\right]\right)$

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• $f = (f_1, \cdots, f_k)$: a multiflow

• congestion of $a \in A$ due to f:

$$\sum_{j\in\left[k\right]}f_{j}\left(\mathsf{N}_{D}^{\textit{in}}\left[\textit{a}\right]\right)$$

• congestion of a^+ due to f:

 $\sum_{a \in A} g\left(a\right) \sum_{j \in [k]} f_{j}\left(a\right)$

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• $f = (f_1, \cdots, f_k)$: a multiflow

• congestion of $a \in A$ due to f:

$$\sum_{j\in[k]}f_{j}\left(\mathsf{N}_{D}^{jn}\left[\mathsf{a}\right]\right)$$

• *congestion* of *a*⁺ due to *f*:

$$\sum_{a\in A}g\left(a
ight)\sum_{j\in\left[k
ight]}f_{j}\left(a
ight)$$

• bottleneck congestion of f

$$\max\left\{\Delta_{D}^{in}\left(\sum_{j\in[k]}f_{j}\right),\sum_{a\in\mathcal{A}}g\left(a\right)\sum_{j\in[k]}f_{j}\left(a\right)\right\}$$

Interference/Budget-Aware Costs and Lengths

• congestion cost of $a \in A$ due to f:

$$y_f(a) = (1+\varepsilon)^{\sum_{j \in [k]} f_j(N_D^{in}[a])}$$

• congestion cost of $a \in A$ due to f:

$$y_f(\mathbf{a}) = (1+\varepsilon)^{\sum_{j \in [k]} f_j(N_D^{in}[\mathbf{a}])}$$

• congestion cost of a^+ due to f:

$$y_f(a^+) = (1+\varepsilon)^{\sum_{a\in A}g(a)\sum_{j\in [k]}f_j(a)}$$

• congestion cost of $a \in A$ due to f:

$$y_f(a) = (1+\varepsilon)^{\sum_{j \in [k]} f_j(N_D^{in}[a])}$$

• congestion cost of a^+ due to f:

$$y_f(a^+) = (1+\varepsilon)^{\sum_{a \in A} g(a) \sum_{j \in [k]} f_j(a)}$$

• *length* of $a \in A$ due to f:

 $\widehat{y}_{f}\left(a\right) = y_{f}\left(N_{D}^{out}\left[a\right]\right) + y_{f}\left(a^{+}\right)g\left(a\right)$

$$\begin{array}{l} \forall j \in [k], f_j \leftarrow \mathbf{0}; \\ \text{repeat} \left\lceil \frac{(m+1)\ln(m+1)}{\ln(1+\varepsilon) - \frac{\varepsilon}{1+\varepsilon}} \right\rceil \text{ times} \\ \forall j \in [k], P_j \leftarrow \text{ a shortest } j\text{-path w.r.t. } \widehat{y}_f; \\ j \leftarrow \arg \max_{j \in [k]} \frac{w_j}{\widehat{y}_f(P_j)}; \\ \delta \leftarrow \frac{1}{\max\left(\max_{a \in A} |P_j \cap N_D^{in}[a]|, g(P_j)\right)}; \\ \forall a \in P_j, f_j(a) \leftarrow f_j(a) + \delta; \end{array}$$

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$$\begin{array}{l} \forall j \in [k], f_j \leftarrow \mathbf{0}; \\ \text{repeat} \left\lceil \frac{(m+1)\ln(m+1)}{\ln(1+\varepsilon) - \frac{\varepsilon}{1+\varepsilon}} \right\rceil \text{ times} \\ \forall j \in [k], P_j \leftarrow \text{ a shortest } j\text{-path w.r.t. } \widehat{y}_f; \\ \sigma \leftarrow \frac{1}{\max\left\{ \max_{a \in A} \sum\limits_{j \in [k]} w_j \left| N_D^{in}[a] \cap P_j \right|, \sum\limits_{j \in [k]} w_j g(P_j) \right\}}; \\ \forall j \in [k] \text{ and } a \in P_j, f_j(a) \leftarrow f_j(a) + \sigma w_j; \end{array}$$

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